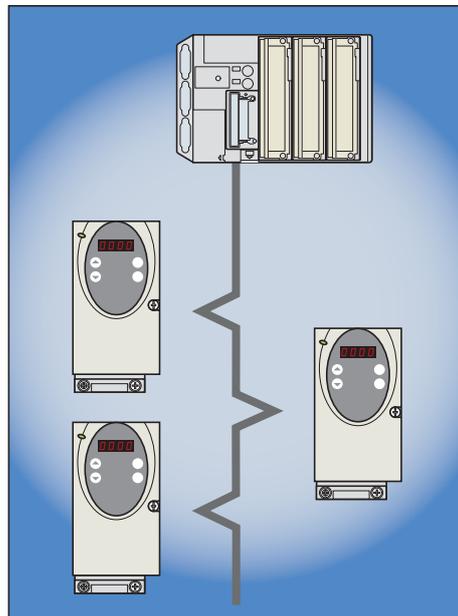


Altivar 31

User's manual

Communication variables



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NOTE

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General

The Altivar 31 can be connected directly to Modbus and CANopen buses by means of an RJ45 connector, which supports both protocols. The communication function provides access to the drive's configuration, adjustment, control and monitoring functions.

The "Communication variables" User's Manual defines the drive control processes and the drive variables which can be accessed by these buses.

It supplements each of the following manuals:

- Modbus
- CANopen

These documents should be referred to for the hardware and software setup specific to each bus.

We also recommend consulting the Programming Manual for additional explanations (operation, factory settings, etc). If the PowerSuite software workshop is used, consult the on-line help provided.

The communication variables are listed with:

- Their address **••••** in decimal format for Modbus
- Their index and subindex address **••••/••** in hexadecimal format for CANopen

They are grouped into several different tables according to the following criteria:

- DRIVECOM variables
- control variables
- monitoring variables
- identification variables
- configuration and adjustment variables

Read/write

Whether the parameters have read and/or write access is indicated in the "Read/Write" column with the following codes:

- R: read only, drive stopped or running
- R/WS: read access when drive stopped or running and write access only when drive stopped
- R/W: read and write access when drive stopped or running

Authorized addresses



Only the addresses and values defined in this document can be used. Any other address or value must be considered to be reserved and must never be written. Failure to observe this precaution may result in malfunctions.

Control modes

Control and reference channels

The control and the reference may originate from different channels:

- the terminal block
- the built-in keypad (ATV31...A only)
- the remote display terminal
- Modbus
- CANopen

These channels are managed:

- either in priority mode for compatibility with the ATV28
- or in deterministic mode

The "Function access level (LAC)" and "Mixed mode (CHCF)" parameters are used to select the run mode. Operation is described in detail in the Programming Manual ("Control menu" section).

Priority stops

In line mode, stop requests which can be activated by the terminals or by the remote display terminal always have priority:

Type of stop	From	Drivecom state reached	Actions for restoring control of the Altivar using the fieldbus
Fast stop	LI2 to LI6	"Operation enabled"	- Set the logic input assigned to the "fast stop" function to 1 (active at 0)
DC injection stop	LI2 to LI6	"Operation enabled"	- Set the logic input assigned to the "injection stop" function to 0 (active at 1)
Freewheel stop	LI2 to LI6	"Switch on disabled"	- Set the logic input assigned to the "freewheel stop" function to 1 (active at 0) - Perform the transitions required to return the drive to "run" status
3-wire control stop via STOP logic input (LI1)	LI1 (3-wire control)	"Switch on disabled"	- Set the logic input assigned to STOP to 1 (active at 0) - Perform the transitions required to return the drive to "run" status
Stop by the display terminal	STOP key (1)	"Switch on disabled"	- Release the Stop key - Perform the transitions required to return the drive to "run" status

(1) Unless the PSt parameter has been set to "NO"

Communication bus monitoring

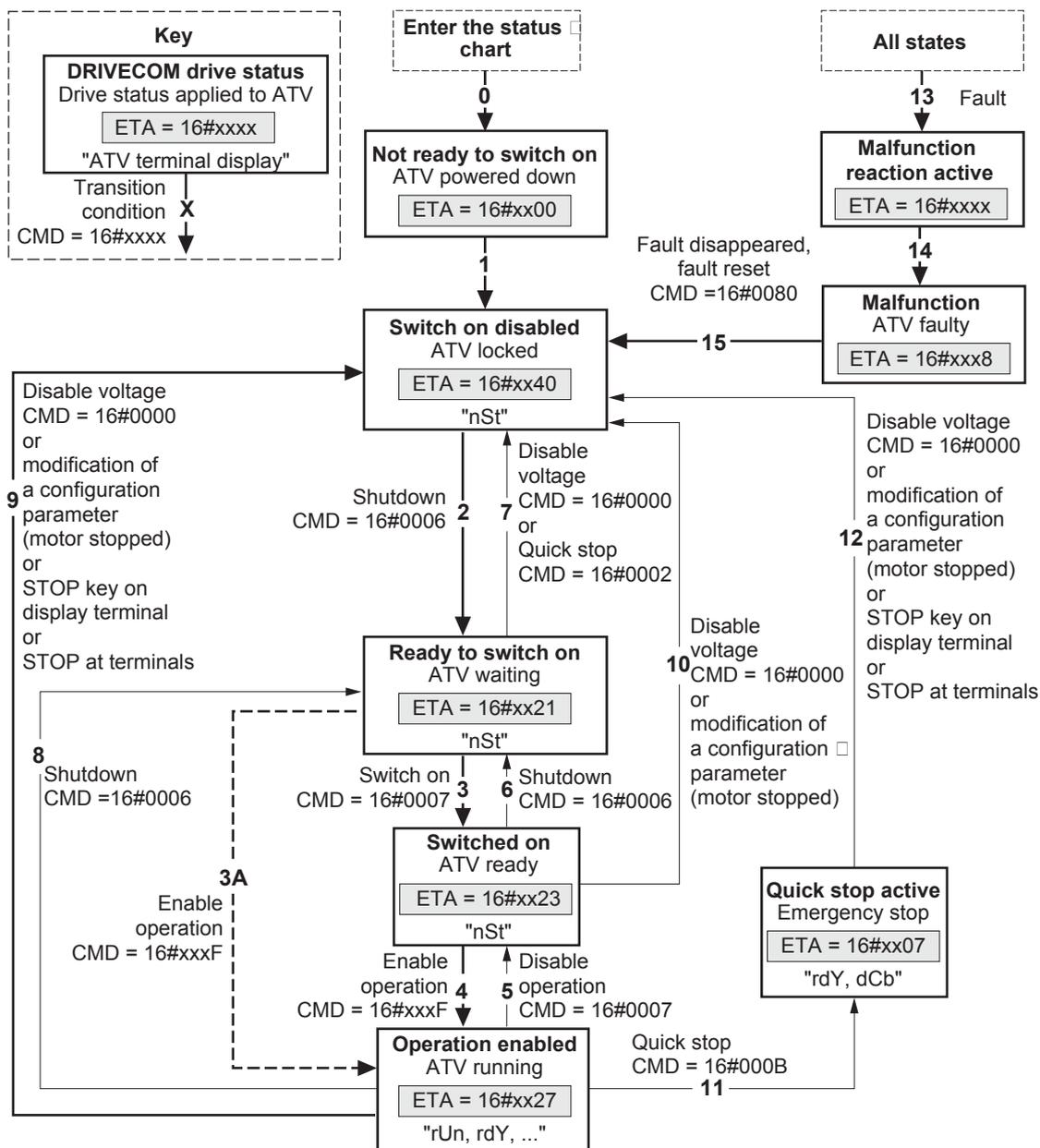
The drive behaviour in the event of loss of communication can be configured via the "SLL" parameter (page [47](#)) for Modbus or the "COL" parameter (page [47](#)) for CANopen. This configuration is saved if the power supply is disconnected. In its factory setting, loss of communication triggers a fault (COF for CANopen or SLF for Modbus) with freewheel stopping.



Bit 14 (NTO) of "Extended control word (CMI)" is also used to inhibit Modbus communication monitoring. This configuration is not saved if the power supply is disconnected. For safety reasons, inhibiting the communication fault should be restricted to the debug phase or to special applications.

Supervision and control in LINE mode

DRIVECOM status chart



<p>Examples:</p> <p>ETA = 16#0627 : Normal stop or □ Forward operation, speed reached</p> <p>ETA = 16#8627 : Reverse operation, speed reached</p> <p>ETA = 16#0227 : Forward operation, ACC or DEC</p> <p>ETA = 16#8227 : Reverse operation, ACC or DEC</p>	<p>Examples (default configuration):</p> <p>CMD = 16#000F : Forward operation</p> <p>CMD = 16#080F : Reverse operation</p> <p>CMD = 16#100F : Stop (configured by "Stt")</p> <p>CMD = 16#200F : DC injection stop</p> <p>CMD = 16#400F : Fast stop</p>
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Any "Operation enabled" output except "Quick stop" = freewheel stop

Supervision and control in LINE mode

The Altivar control process using the communication bus conforms to the CANopen DS402 profile status chart compatible with the DRIVECOM standard. Each state represents an aspect of the internal behaviour of the drive.

This chart evolves according to whether the control word is sent (CMD W8501) or an event occurs (example: lock following malfunction). The drive status can be identified by the value of the status word (ETA W3201).

Not ready to switch on (Initialization):

Communication is being initialized.
Transient state invisible to the communication bus.

Switch on disabled (Configuration):

Initialization of the drive is complete.
The configuration and adjustment parameters can be modified.
If all or part of the configuration and settings are to be loaded, we recommend disabling the consistency check function during the transfer (CMI W8504, bit 15 = 1). On completion of the transfer, the consistency check must be enabled (CMI W8504, bit 15 = 0).
The drive is locked.

Ready to switch on and Switched on (Drive initialized):

The configuration and adjustment parameters can be modified. In the "Switched on" state, modifying a configuration parameter returns the drive to the "Switch on disabled" state.
The drive is locked.
The power stage of the drive is ready to operate, but voltage has not yet been applied to the output.

Operation enabled (Operational):

Only the adjustment parameters can be modified. Modifying a configuration parameter (motor stopped) returns the drive to the "Switch on disabled" state.
The drive functions are activated and voltage is applied to the motor terminals.
Auto-tuning (tUn) requires an injection of current. The drive must therefore be in this state for this command.

Quick stop active (Emergency stop active):

Fast stop.
Restarting is only possible after the drive has changed to the "Switch on disabled" state.

Malfunction reaction active (Reaction on fault):

Transient state during which the drive performs an action appropriate to the type of fault.
The drive function is disabled.

Malfunction (Fault):

The drive is faulty.
The drive is locked.

Supervision and control in LINE mode

CMD control word (W8501)

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
Fault reset	0	0	0	Enable operation	Quick stop (active at 0)	Disable voltage (active at 0)	Switch on
bit 15	bit 14	bit 13	bit 12	bit 11	bit 10	bit 9	bit 8
(1)	(1)	(1)	(1)	(1)	0	0	0

(1) This bit action depends on the LAC "Access levels" parameter and the functions configured by the user. For example, to use bit 15 to switch the ramp, simply configure LAC = L3 (Access to advanced functions and management of mixed modes) and set the "Ramp switching rPS" configuration parameter to Cd15.

Command	Transition address	Final state	bit 7	bit 3	bit 2	bit 1	bit 0	Typical value of CMD (W8501)
			Reset	Enable operation	Quick stop	Disable voltage	Switch on	
Shut down	2, 6, 8	Ready to switch on	x	x	1	1	0	16#0006
Switch on	3	Switched on	x	x	1	1	1	16#0007
Enable operation	4	Operation enabled	x	1	1	1	1	16#000F
Disable operation	5	Switched on	x	0	1	1	1	16#0007
Disable voltage	7, 9, 10, 12	Switch on disabled	x	x	x	0	x	16#0000
Quick stop	11	Quick stop active	x	x	0	1	x	16#000B or 16#0002
	7, 10	Switch on disabled						
Fault reset	15	Switch on disabled	0 → 1	x	x	x	x	16#0080

x: State not significant
0 → 1: Change from 0 to 1

Supervision and control in LINE mode

ETA status word (W3201)

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
Alarm	Switch on disabled	Quick stop active at 0	0 (1)	Malfunction	Operation enabled	Switched on	Ready to switch on
bit 15	bit 14	bit 13	bit 12	bit 11	bit 10	bit 9	bit 8
Direction of rotation	Stop via STOP key	0	0	Reference exceeded	Reference reached	Forced local mode (active at 0)	0

State	bit 6	bit 5	bit 3	bit 2	bit 1	bit 0	ETA (W3201) masked by 16#006F
	Switch on disabled	Quick stop	Malfunction	Operation enabled	Switched on	Ready to switch on	
Not ready to switch on	0	x	0	0	0	0	16#0000 16#0020
Switch on disabled	1	x	0	0	0	0	16#0040 16#0060
Ready to switch on	0	1	0	0	0	1	16#0021
Switched on	0	1	0	0	1	1	16#0023
Operation enabled	0	1	0	1	1	1	16#0027
Malfunction	0	x	1	0	0	0	16#0008 16#0028
Malfunction reaction active	0	x	1	1	1	1	16#000F 16#002F
Quick stop active	0	0	0	1	1	1	16#0007

x: State not significant

(1) Bit 4 of the ETA status word corresponds to DRIVECOM's "Voltage disabled".

Function compatibility

Incompatible functions

The following functions will be inaccessible or deactivated in the cases described below:

Automatic restart

This is only possible for 2-wire level detection control (tCC = 2C and tCt = LEL or PFO).

Flying restart

This is only possible for 2-wire level detection control (tCC = 2C and tCt = LEL or PFO).
This function is locked if automatic injection on stopping is configured as DC (AdC = Ct).

Reverse

On the ATV31●●●A range only, this function is locked if local control is active (tCC = LOC).

Function compatibility table

The choice of application functions may be limited by the number of I/O and by the fact that some functions are incompatible with one another. Functions which are not listed in this table are fully compatible.

If there is an incompatibility between functions, the first function configured will prevent the remainder being configured.

To configure a function, first check that the incompatible functions are not assigned, especially "Preset speeds" and "Summing inputs" which are assigned by default in the factory setting.

	Summing inputs	+/- speed (1)	Management of limit switches	Preset speeds	PI regulator	Jog operation	Brake sequence	DC injection stop	Fast stop	Freewheel stop
Summing inputs	●			↑	●	↑				
+/- speed (1)	●	●		●	●	●				
Management of limit switches			●		●					
Preset speeds	↑	●		●	↑					
PI regulator	●	●	●	●	●	●	●			
Jog operation	↑	●		↑	●	●	●			
Brake sequence					●	●	●	●		
DC injection stop							●	●		↑
Fast stop								●	●	↑
Freewheel stop								↑	↑	●

(1) Excluding special application with reference channel Fr2.

● Incompatible functions □ Compatible functions ■ N/A

Priority functions (functions which cannot be active at the same time):

← ↑ The function indicated by the arrow has priority over the other.

Stop functions have priority over run commands.

Speed references via logic command have priority over analog references.

⚠ Logic and analog input application functions

Each of the functions can be assigned to one of the inputs.

A single input can activate several functions at the same time (reverse and 2nd ramp for example). The user must therefore ensure that these functions can be used at the same time.

DRIVECOM variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
8601	6040	CMDD	R/W	<p>DRIVECOM control word Identical to CMD (page 14). bit 0: "Switch on": active at 1 bit 1: "Disable Voltage": active at 0 bit 2: "Quick Stop": active at 0 bit 3: "Enable Operation": active at 1 bits 4 to 6: Reserved: set to 0 bit 7: Fault reset: active on rising edge 0 -> 1 bits 8 to 10: Reserved: set to 0</p> <p>For "Access level" LAC (page 30) = L1 or L2:</p> <p>bit 11 = 0: Forward direction command bit 11 = 1: Reverse direction command bit 12 = 0: No action bit 12 = 1: Stop command depending on the Stt "Stop type" parameter bit 13 = 0: No action bit 13 = 1: Injection stop command bit 14 = 0: No action bit 14 = 1: Fast stop command bit 15: Reserved: set to 0</p> <p>For "Access level" LAC (page 30) = L3:</p> <p>Factory assignments bit 11 = 0: Forward direction command bit 11 = 1: Reverse direction command bit 12 = 0: No action bit 12 = 1: Stop command depending on the Stt "Stop type" parameter bit 13: No action bit 14: No action bit 15: No action</p> <p>These 5 bits can be assigned to functions. For example, to use bit 15 to switch the ramp, simply set the "Ramp switching" rPS configuration parameter (page 33) to Cd15.</p>
8602	6042	LFRD	R/W	<p>Speed reference via the bus (signed value) DSP402: vl target velocity DRIVECOM: Nominal speed value Unit: <ul style="list-style-type: none"> • 1 = 1 rpm if bit 9 of CMI (page 15) = 0 • 1 ≈ 0.018 Hz (resolution 32767 points = 600 Hz) if bit 9 of CMI = 1 </p>
8603	6041	ETAD	R	<p>DRIVECOM status word Identical to ETA (page 16). bit 0: Ready to switch on bit 1: Switched on bit 2: Operation enabled bit 3 = 0: No fault bit 3 = 1: Malfunction, fault present (FAI) bit 4: Voltage disabled bit 5: Quick stop bit 6: Switch on disabled bit 7 = 0: No alarm bit 7 = 1: Alarm present bit 8: Reserved bit 9 = 0: Forced local mode in progress (FLO) bit 9 = 1: No forced local mode bit 10 = 0: Reference not reached (transient state) bit 10 = 1: Reference reached (steady state) bit 11 = 0: LFRD reference normal bit 11 = 1: LFRD reference exceeded (< LSP or > HSP) Caution: LFRD is expressed in rpm, LSP and HSP in Hz bits 12 and 13: Reserved bit 14 = 0: No stop imposed by STOP key on built-in keypad (ATV31...A) or on the remote display terminal bit 14 = 1: Stop imposed by STOP key on built-in keypad (ATV31...A) or on the remote display terminal bit 15 = 0: Forward rotation (output frequency) bit 15 = 1: Reverse rotation (output frequency)</p>

DRIVECOM variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
8605	6043	FRHD	R	Speed reference (signed ramp input) DSP402: vl velocity demand DRIVECOM: Reference speed variable Unit: 1 rpm
8604	6044	RFRD	R	Output speed (signed value) DSP402: vl control effort DRIVECOM: Actual speed value Unit: <ul style="list-style-type: none"> • 1 = 1 rpm if bit 9 of CMI (page 15) = 0 • 1 ≈ 0.018 Hz (resolution 32767 points = 600 Hz) if bit 9 of CMI = 1
8606	603F	ERRD	R	Fault code DSP402: Error code DRIVECOM: Malfunction code 0000H = "nOF": No fault saved 1000H = "CrF": Capacitor pre-charge fault or = "OLF": Motor overload fault or = "SOF": Motor overspeed fault 2310H = "OCF": Overcurrent fault 2320H = "SCF": Impeding short-circuit fault or = "SCF": Power module fault, specific to ATV31●D15● 2330H = "SCF": Motor short-circuit fault (to earth) 2340H = "SCF": Motor short-circuit fault (phase to phase) 3110H = "OSF": Line supply overvoltage fault 3120H = "USF": Line supply undervoltage fault 3130H = "PHF": Line supply phase loss fault 3310H = "ObF": DC bus overvoltage fault or = "OPF": Motor phase loss fault or = "OPF": Motor phase loss fault - 3 phases 4210H = "OHF": Drive overheating fault 5520H = "EEF": EEPROM memory fault 6100H = "InF": Internal fault 6300H = "CFF": Configuration (parameters) incorrect or = "CFI": Configuration (parameters) invalid 7300H = "LFF": 4 - 20 mA fault on AI3 7510H = "SLF": Modbus communication fault 8100H = "COF": CANopen communication fault 9000H = "EPF": External fault FF00H = "tnF": Auto-tuning fault FF01H = "bLF": Brake control fault
8607 - 8608	6046 / 1	SMIL	R/W	Min. speed DSP402: vl velocity min amount DRIVECOM: Speed min amount Low speed, equivalent to LSP (page 23), but in rpm Unit: 1 rpm 32-bit word (low order: 8607, high order: 8608) Adjustment range: 0 to HSP (page 23)
8609 - 8610	6046 / 2	SMAL	R/W	Max. speed DSP402: vl velocity max amount DRIVECOM: Speed max amount High speed, equivalent to HSP (page 23), but in rpm Unit: 1 rpm 32-bit word (low order: 8609, high order: 8610) Adjustment range: LSP (page 23) to tFR (page 27)
8611 - 8612	6048 / 1	SPAL	R/W	Acceleration - Speed delta Speed for calculation of acceleration ramp Unit: 1 rpm 32-bit word (low order: 8611, high order: 8612) Adjustment range: 1 to 65535
8613	6048 / 2	SPAT	R/W	Acceleration - Time delta Time for calculation of acceleration ramp (time to go from 0 to SPAL) Unit: 1 s Adjustment range: 0 to 65535

DRIVECOM variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
8614 - 8615	6049 / 1	SPDL	R/W	Deceleration - Speed delta Speed for calculation of deceleration ramp Unit: 1 rpm 32-bit word (low order: 8614, high order: 8615) Adjustment range: 1 to 65535
8616	6049 / 2	SPDT	R/W	Deceleration - Time delta Time for calculation of deceleration ramp (time to go from SPDL to 0) Unit: 1 s Adjustment range: 0 to 65535

Control variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
8501	2037 / 2	CMD	R/W	<p>Control word bit 0: "Switch on": active at 1 bit 1: "Disable Voltage": active at 0 bit 2: "Quick Stop": active at 0 bit 3: "Enable Operation": active at 1 bits 4 to 6: Reserved: set to 0 bit 7: Fault reset: active on rising edge 0 -> 1 bits 8 to 10: Reserved: set to 0</p> <p>For "Access level" LAC (page 30) = L1 or L2:</p> <p>bit 11 = 0: Forward direction command bit 11 = 1: Reverse direction command bit 12 = 0: No action bit 12 = 1: Stop command depending on the Stt "Stop type" parameter bit 13 = 0: No action bit 13 = 1: Injection stop command bit 14 = 0: No action bit 14 = 1: Fast stop command bit 15: Reserved: set to 0</p> <p>For "Access level" LAC (page 30) = L3:</p> <p>Factory assignments bit 11 = 0: Forward direction command bit 11 = 1: Reverse direction command bit 12 = 0: No action bit 12 = 1: Stop command depending on the Stt "Stop type" parameter bit 13: No action bit 14: No action bit 15: No action</p> <p>These 5 bits can be assigned to functions. For example, to use bit 15 to switch the ramp, simply set the "Ramp switching" rPS configuration parameter (page 33) to Cd15.</p>
8502	2037 / 3	LFr	R/W	<p>Frequency reference via the bus (signed value) Unit: • 1 = 0.1 Hz if bit 9 of CMI (page 15) = 0 • 1 ≈ 0.018 Hz (resolution 32767 points = 600 Hz) if bit 9 of CMI = 1</p>
8503	2037 / 4	PISP	R/W	<p>PI regulator reference via the bus Unit: 0.1% Adjustment range: 0 to 1000</p>

Control variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
8504	2037 / 5	CMI	R/W	<p>Extended control word</p> <p>bit 0 = 0: No action bit 0 = 1: Recall factory settings command. This bit automatically resets to 0 when the request is taken into account. It is only active when the drive has come to a complete stop: ETI.4 = ETI.5 = 0.</p> <p>bit 1 = 0: No action bit 1 = 1: Save configuration/adjustments in EEPROM if voltage is sufficient (no USF fault). This bit automatically resets to 0 when the request is taken into account. During saving (ETI.0 = 1), parameters cannot be written.</p> <p>bits 2 and 3: Reserved</p> <p>bit 4 = 0: No action bit 4 = 1: Ramp switching command</p> <p>bits 4 to 8: Reserved</p> <p>bit 9 = 0: Normal resolution (references, output speed and output frequency in physical units: rpm and Hz) bit 9 = 1: High resolution (references, output speed and output frequency in 32767 points for 600 Hz)</p> <p>bits 10 to 12: Reserved</p> <p>bit 13 = 0: Drive not locked on standstill bit 13 = 1: Drive locked on standstill</p> <p>bit 14 = 0: Control with Modbus communication monitoring bit 14 = 1: Control with no Modbus communication monitoring (NTO)</p> <p> For safety reasons, inhibiting the Modbus communication fault (NTO) should be restricted to the debug phase or to special applications.</p> <p>bit 15 = 0: Parameter consistency check bit 15 = 1: No parameter consistency check + drive locked on standstill (switching this bit to 0 will revalidate all parameters)</p>
5240	2016 / 29	IOLR	R/W	<p>Value of logic I/O</p> <p>(0 = inactive, 1 = active)</p> <p>bits 0 to 7: Not accessible in write mode</p> <p>bit 8: Value of "R1" relay output, accessible in write mode if R1 is not assigned</p> <p>bit 9: Value of "R2" relay output, accessible in write mode if R2 is not assigned</p> <p>bit 10: Value of "LO" logic output, accessible in write mode if LO is not assigned</p> <p>bits 11 to 13: Reserved</p> <p>bit 14: Not accessible in write mode</p> <p>bit 15: Reserved</p>
5261	2016 / 3E	AO1R	R/W	<p>Value of the analog output</p> <p>AO1R is accessible in write mode if dO (page 29) is not assigned</p> <p>Variation range: 0 to 10000</p> <p>The value 10000 corresponds to 10V if AO1t = 10U, or to 20 mA if AO1t = OA or 4A (page 28)</p>

Monitoring variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
3201	2002 / 2	ETA	R	Status word bit 0: Ready to switch on bit 1: Switched on bit 2: Operation enabled bit 3 = 0: No fault bit 3 = 1: Malfunction, fault present (FAI) bit 4: Voltage disabled (still equals 0) bit 5: Quick stop bit 6: Switch on disabled bit 7 = 0: No alarm bit 7 = 1: Alarm present bit 8: Reserved bit 9 = 0: Forced local mode in progress (FLO) bit 9 = 1: No forced local mode bit 10 = 0: Reference not reached (transient state) bit 10 = 1: Reference reached (steady state) bit 11 = 0: LFRD reference normal bit 11 = 1: LFRD reference exceeded (< LSP or > HSP) Caution: LFRD is expressed in rpm, LSP and HSP in Hz bits 12 and 13: Reserved bit 14 = 0: No stop imposed by STOP key on built-in keypad (ATV31...A) or on the remote display terminal bit 14 = 1: Stop imposed by STOP key on built-in keypad (ATV31...A) or on the remote display terminal bit 15 = 0: Forward rotation (output frequency) bit 15 = 1: Reverse rotation (output frequency)
3202	2002 / 3	rFr	R	Output frequency applied to the motor (signed value) Unit: <ul style="list-style-type: none"> • 1 = 0.1 Hz if bit 9 of CMI (page 15) = 0 • 1 ≈ 0.018 Hz (resolution 32767 points = 600 Hz) if bit 9 of CMI = 1
3203	2002 / 4	FrH	R	Frequency reference before ramp (absolute value) Unit: 0.1 Hz
3204	2002 / 8	LCr	R	Current in the motor Unit: 0.1 A
3205	2002 / 6	Otr	R	Motor torque Unit: 1% 100% = Nominal motor torque, calculated using the configuration parameters.
3211	2002 / C	OPr	R	Motor power Unit: 1% 100% = Nominal motor power, calculated using the configuration parameters.
3207	2002 / 5	ULn	R	Line voltage Unit: 0.1 V (gives the line voltage via the DC bus, motor running or stopped)
3209	2002 / A	tHd	R	Drive thermal state Unit: 1% 100% = Nominal thermal state 118% = "OHF" threshold (drive overheating)
3210	2002 / B	TDM	R	Max. thermal state reached by the drive Unit: 1% 100% = Nominal thermal state 118% = "OHF" threshold (drive overheating) Automatically reset to zero when the drive is powered down.
9630	2042 / 1F	tHr	R	Motor thermal state Unit: 1% 100% = Nominal thermal state 118% = "OLF" threshold (motor overload)
3231	2002 / 20	rtH	R	Operating time Unit: 1 Hour Factory setting: 0 Adjustment range: 0 to 65535 Total time the motor has been powered up. Can be reset to zero by the rPr parameter (see page 48).

Monitoring variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
12002	205A / 3	USPL	R	Motor speed in customer units - Low order Unit: 1 USPL/USPH = rFr x SdS on 32 bits (see pages 25 and 16).
12003	205A / 4	USPH	R	Motor speed in customer units - High order Unit: 1 USPL/USPH = rFr x SdS on 32 bits (see pages 25 and 16).
3206	2002 / 7	ETI	R	Extended status word bit 0 = 0: Write parameters authorized bit 0 = 1: Write parameters not authorized (the drive is in the process of saving the current parameters from the RAM to the EEPROM) bit 1 = 0: No parameter consistency check + drive locked on standstill bit 1 = 1: Parameter consistency check bit 2 = 0: Fault reset not authorized bit 2 = 1: Fault reset authorized bit 3: Reserved bit 4 = 0: Motor stopped bit 4 = 1: Motor running bit 5 = 0: No DC injection bit 5 = 1: DC injection bit 6 = 0: Drive in steady state bit 6 = 1: Drive in transient state bit 7 = 0: No motor thermal overload alarm bit 7 = 1: Motor thermal overload alarm bit 8 = 0: No alarm if excessive braking bit 8 = 1: Alarm if excessive braking bit 9 = 0: Drive not accelerating bit 9 = 1: Drive accelerating bit 10 = 0: Drive not decelerating bit 10 = 1: Drive decelerating bit 11 = 0: No current limit alarm bit 11 = 1: Current limit alarm bit 12 = 0: Fast stop not in progress bit 12 = 1: Fast stop in progress bit 14 = 0 and bit 13 = 0: ATV controlled via terminal block or built-in keypad (ATV31....A) bit 14 = 0 and bit 13 = 1: ATV controlled via the remote display terminal bit 14 = 1 and bit 13 = 0: ATV controlled via ModBus bit 14 = 1 and bit 13 = 1: ATV controlled via CanOpen bit 15 = 0: Forward rotation requested (reference) bit 15 = 1: Reverse rotation requested (reference)
3250	2002 / 33	LRS1	R	Extended status word No. 1 bit 0: Reserved bit 1 = 0: No drive fault bit 1 = 1: Drive fault bit 2 = 0: Motor stopped bit 2 = 1: Motor running bit 3: Reserved bit 4 = 0: Frequency threshold (Ftd) not reached bit 4 = 1: Frequency threshold (Ftd) reached bit 5 = 0: High speed not reached bit 5 = 1: High speed reached bit 6 = 0: Current threshold (Ctd) not reached bit 6 = 1: Current threshold (Ctd) reached bit 7 = 0: Speed reference not reached bit 7 = 1: Speed reference reached bit 8 = 0: No motor thermal overload alarm bit 8 = 1: Motor thermal overload alarm bit 9 = 0: No brake control (brake engaged) bit 9 = 1: Brake control in progress (brake released) bits 10 and 11: Reserved bit 12 = 0: No loss of 4-20 mA fault bit 12 = 1: Loss of 4-20 mA fault bit 13: Reserved bit 14 = 0: No drive thermal overload alarm bit 14 = 1: Drive thermal overload alarm bit 15: Reserved

Monitoring variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
3252	2002 / 35	LRS3	R	Extended status word No. 3 bit 0 = 0: The reference is given by Fr1 bit 0 = 1: The reference is given by Fr2 bit 1 = 0: The command is given by Fr1 or Cd1 bit 1 = 1: The command is given by Fr2 or Cd2 bit 2 = 0: ACC and DEC are used as ramp parameters bit 2 = 1: ACC2 and DEC2 are used as ramp parameters bit 3 = 0: CLI is used for current limiting bit 3 = 1: CL2 is used for current limiting bits 4 to 10: Reserved bit 11 = 0: Motor 1 is not used bit 11 = 1: Motor 1 is used bit 12 = 0: Motor 2 is not used bit 12 = 1: Motor 2 is used bits 13 to 15: Reserved
5240	2016 / 29	IOLR	R	Value of logic I/O (0 = inactive, 1 = active) bit 0: Value of logic input "LI1" bit 1: Value of logic input "LI2" bit 2: Value of logic input "LI3" bit 3: Value of logic input "LI4" bit 4: Value of logic input "LI5" bit 5: Value of logic input "LI6" bit 6: Reserved bit 7: Keypad presence: 0 = absent, 1 = present bit 8: Value of "R1" relay output, also accessible in write mode if R1 is not assigned bit 9: Value of "R2" relay output, also accessible in write mode if R2 is not assigned bit 10: Value of "LO" logic output, also accessible in write mode if LO is not assigned bit 11: Reserved bit 12: Reserved bit 13: Reserved bit 14: 0 = AOC/AOV logic output, 1 = AOC/AOV analog output bit 15: Reserved
5241	2016 / 2A	AIPC	R	Value of analog input AIP (ATV31....A drive potentiometer) Unit: 1 mV Variation range: 0 to 10000
5242	2016 / 2B	AI1C	R	Value of analog input AI1 Unit: 1 mV Variation range: 0 to 10000
5243	2016 / 2C	AI2C	R	Value of analog input AI2 Unit: 1 mV Variation range: -10000 to 10000
5244	2016 / 2D	AI3C	R	Value of analog input AI3 Unit: 1 μ A Variation range: 0 to 20000
5261	2016 / 3E	AO1R	R	Value of the analog output AO1R is also accessible in write mode if dO (page 29) is not assigned Variation range: 0 to 10000 The value 10000 corresponds to 10V if AO1t = 10U, or to 20 mA if AO1t = OA or 4A (page 28)

Monitoring variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
7121	2029 / 16	LFt	R	Last fault The fault remains saved even if the fault disappears, but LFt is reset after powering down the drive then powering up again. 0 = "nOF": No fault saved 3 = "CFF": Configuration (parameters) incorrect 4 = "CFI": Configuration (parameters) invalid 5 = "SLF": Modbus communication fault 8 = "EPF": External fault 9 = "OCF": Overcurrent fault 10 = "CrF": Capacitor pre-charge fault 13 = "LFF": 4 - 20 mA fault on AI3 16 = "OHF": Drive overheating fault 17 = "OLF": Motor overload fault 18 = "ObF": DC bus overvoltage fault 19 = "OSF": Line supply overvoltage fault 20 = "OPF": Motor phase loss fault 21 = "PHF": Line supply phase loss fault 22 = "USF": Line supply undervoltage fault 23 = "SCF": Motor short-circuit fault (phase to phase) 24 = "SOF": Motor overspeed fault 25 = "tnF": Auto-tuning fault 26 to 29 = "InF": Internal fault 30 = "EEF": EEPROM memory fault 31 = "SCF": Impeding short-circuit fault 32 = "SCF": Motor short-circuit fault (to earth) 33 = "OPF": Motor phase loss fault - 3 phases 34 = "COF": Communication fault line 2 (CANopen) 35 = "bLF": Brake control fault 36 = "SCF": Power module fault, specific to ATV31●D15●
7201	202A / 2	DP1	R	Past fault No. 1 (Same format as "LFt" page 19)
7202	202A / 3	DP2	R	Past fault No. 2 (Same format as "LFt" page 19)
7203	202A / 4	DP3	R	Past fault No. 3 (Same format as "LFt" page 19)
7204	202A / 5	DP4	R	Past fault No. 4 (Same format as "LFt" page 19)

Monitoring variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
7211	202A / C	EP1	R	Status of past fault No. 1 bit 0 = Same as ETA.1: - 0: Drive not ready - 1: Drive ready (RDY) bit 1 = Same as ETA.5: - 0: Emergency stop in progress - 1: No emergency stop bit 2 = Same as ETA.6: - 0: No SWITCH ON DISABLED status - 1: SWITCH ON DISABLED status bit 3 = Same as ETA.9: Reserved bit 4 = Same as ETA.15: - 0: Forward rotation (output frequency) - 1: Reverse rotation (output frequency) bit 5 = Same as ETI.4: - 0: Motor stopped - 1: Motor running bit 6 = Same as ETI.5: - 0: No DC injection - 1: DC injection bit 7 = Same as ETI.7: - 0: No motor thermal overload alarm - 1: Motor thermal overload alarm bit 8 = Same as ETI.8: Reserved bit 9 = Same as ETI.9: - 0: Drive not accelerating - 1: Drive accelerating bit 10 = Same as ETI.10: - 0: Drive not decelerating - 1: Drive decelerating bit 11 = Same as ETI.11: - 0: No current limit alarm - 1: Current limit alarm bit 12 = Same as ETI.12: Reserved bits 13 and 14 = Same as ETI.13 and ETI.14: - bit 14 = 0 and bit 13 = 0: ATV controlled via terminal block or built-in keypad (ATV31....A) - bit 14 = 0 and bit 13 = 1: ATV controlled via the remote display terminal - bit 14 = 1 and bit 13 = 0: ATV controlled via ModBus - bit 14 = 1 and bit 13 = 1: ATV controlled via CanOpen bit 15 = Same as ETI.15: - 0: Forward rotation requested (reference) - 1: Reverse rotation requested (reference)
7212	202A / D	EP2	R	Status of past fault No. 2 (Same format as "EP1")
7213	202A / E	EP3	R	Status of past fault No. 3 (Same format as "EP1")
7214	202A / F	EP4	R	Status of past fault No. 4 (Same format as "EP1")
6056	201E / 39	ErCO	R	CANopen: error word Unit: 1 Range: 0 to 4 0: "No error" 1: "Bus off error" 2: "Life time error" 3: "CAN overrun" 4: "Heartbeat error"
8541	2037 / 2A	CMI1	R	Image of Modbus extended control word (received by the Modbus channel) Identical to CMI (page 15).

Monitoring variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
8542	2037 / 2B	CMI2	R	Image of CANopen extended control word (received by the CANopen channel) Identical to CMI (page 15).
8521	2037 / 16	LFR1	R	Image of Modbus frequency reference (received by the Modbus channel) Identical to LFr (page 14).
8522	2037 / 17	LFR2	R	Image of CANopen frequency reference (received by the CANopen channel) Identical to LFr (page 14).
8631	2038 / 20	LFD1	R	Image of Modbus speed reference Speed reference received by the Modbus channel Identical to LFRD (page 11)
8632	2038 / 21	LFD2	R	Image of CANopen speed reference Speed reference received by the CANopen channel Identical to LFRD (page 11)
8531	2037 / 20	PIR1	R	Image of Modbus PI reference (received by the Modbus channel) Identical to PISP (page 14).
8532	2037 / 21	PIR2	R	Image of CANopen PI reference (received by the CANopen channel) Identical to PISP (page 14).

Identification variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
3011	2000 / C	NCV	R	Drive rating 0 = unknown 1 = 018 (0.18 kW) 2 = 037 (0.37 kW) 3 = 055 (0.55 kW) 4 = 075 (0.75 kW) 5 = U11 (1.1 kW) 6 = U15 (1.5 kW) 7 = U22 (2.2 kW) 8 = U30 (3 kW) 9 = U40 (4 kW) 10 = U55 (5.5 kW) 11 = U75 (7.5 kW) 12 = D11 (11 kW) 13 = D15 (15 kW)
3012	2000 / D	VCAL	R	Drive voltage 0 = unknown 1 = M2 (200...240 V single phase) 2 = M3X (200...240 V 3-phase) 3 = N4 (380...500 V 3-phase) 4 = S6X (525...600 V 3-phase)
3017	2000 / 12	INV	R	Nominal drive current Unit: 0.1 A
3010	2000 / B	ZON	R	Drive type 0 = unknown 1 = ATV31.....(drive without built-in keypad) 3 = ATV31.....(drive with built-in keypad)
3401	2004 / 2	TSP	R	Drive firmware type The firmware type is specified by an ASCII letter "A": Standard firmware
3302	2000 / 4	UdP	R	Drive firmware version Coded on 2 bytes. - low order byte: firmware upgrade index (UI) in hexadecimal format - high order byte: firmware version (V) in hexadecimal format Example : For V1.2 IE04, UdP = 16#1204

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
3105	2001 / 6	LSP	R/W	Low speed Unit: 0.1 Hz Factory setting: 0 Adjustment range: 0 to HSP (Motor frequency at min. reference)
3104	2001 / 5	HSP	R/W	High speed Unit: 0.1 Hz Factory setting: if bFr = 50: 500, if bFr = 60: 600 Adjustment range: LSP to tFr (Motor frequency at max. reference): Ensure that this setting is suitable for the motor and the application.
9622	2042 / 17	ItH	R/W	Motor thermal protection - max. thermal current Unit: 0.1 A Factory setting: According to drive rating Adjustment range: 0.2 to 1.5 In (1) Set ItH to the nominal current on the motor rating plate. Please refer to OLL on page 47 if you wish to suppress thermal protection. (1) In corresponds to the nominal drive current indicated in the Installation Manual and on the drive rating plate.
9623	2042 / 18	UFR	R/W	IR compensation/Voltage boost Unit: 1% Factory setting: 20 Adjustment range: 0 to 100 - For UFt (page 27) = n or nLd: IR compensation - For UFt = L or P: Voltage boost Used to optimize torque at very low speed (increase UFR if the torque is insufficient). Check that the value of UFR is not too high for when the motor is warm (risk of instability).  Modifying UFt (page 27) will cause UFR to return to the factory setting (20%).
9620	2042 / 15	FLG	R/W	Frequency loop gain Unit: 1% Factory setting: 20 Adjustment range: 1 to 100 Parameter active only if UFt (page 27) = n or nLd. The FLG parameter adjusts the following of the speed ramp on the basis of the inertia of the machine being driven. Too high a gain may result in operating instability.
9621	2042 / 16	StA	R/W	Frequency loop stability Unit: 1% Factory setting: 20 Adjustment range: 1 to 100 Parameter active only if UFt (page 27) = n or nLd. Used to adapt the return to steady state after a speed transient (acceleration or deceleration), according to the dynamics of the machine. Gradually increase the stability to avoid any overspeed.
9625	2042 / 1A	SLP	R/W	Slip compensation Unit: 1% Factory setting: 100 Adjustment range: 0 to 150 Parameter active only if UFt (page 27) = n or nLd. Used to adjust the slip compensation value fixed by nominal motor speed. The speeds given on motor rating plates are not necessarily exact. If slip setting < actual slip: the motor is not rotating at the correct speed in steady state. If slip setting > actual slip: the motor is overcompensated and the speed is unstable.
11301	2053 / 2	JPF	R/W	Skip frequency Unit: 0.1 Hz Factory setting: 0 Adjustment range: 0 to 5000 Prevents prolonged operation at a frequency range of ± 1 Hz around JPF. This function prevents a critical speed which leads to resonance. Setting the function to 0 renders it inactive.

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
11302	2053 / 3	JF2	R/W	2nd skip frequency Unit: 0.1 Hz Factory setting: 0 Adjustment range: 0 to 5000 Prevents prolonged operation at a frequency range of ± 1 Hz around JF2. This function prevents a critical speed which leads to resonance. Setting the function to 0 renders it inactive.
9201	203E / 2	CLI	R/W	Current limit Unit: 0.1 A Factory setting: 1.5 In (1) Adjustment range: 0.25 to 1.5 In (1) Used to limit the torque and the temperature rise of the motor. (1) In corresponds to the nominal drive current indicated in the Installation Manual and on the drive rating plate.
11701	2057 / 2	tLS	R/W	Low speed operating time Unit: 0.1 s Factory setting: 0 (no time limit) Adjustment range: 0 to 9999 Following operation at LSP for a defined period, a motor stop is requested automatically. The motor restarts if the frequency reference is greater than LSP and if a run command is still present. Caution, value 0 corresponds to an unlimited time.
11003	2050 / 4	Ftd	R/WS	Motor frequency threshold Unit: 0.1 Hz Factory setting: bFr Adjustment range: 0 to 5000 Motor frequency threshold above which the relay contact (R1 or R2 = FtA) closes or output AOV = 10 V (dO = StA)
11002	2050 / 3	ttd	R/WS	Motor thermal state threshold Unit: 1% Factory setting: 100 Adjustment range: 0 to 118 Motor thermal state threshold above which the relay contact (R1 or R2 = tSA) closes or output AOV = 10 V (dO = tSA)
11001	2050 / 2	Ctd	R/WS	Motor current threshold Unit: 0.1 A Factory setting: In (1) Adjustment range: 0 to 1.5 In (1) Motor current threshold above which the relay contact (R1 or R2 = CtA) closes or output AOV = 10 V (dO = CtA) (1) In corresponds to the nominal drive current indicated in the Installation Manual and on the drive rating plate.

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
12001	205A / 2	SdS	R/W	USPL/USPH scale factor (USPL/USPH = rFr x SdS) See USPL/USPH page 17 . Unit: 0.1 Factory setting: 300 Adjustment range: 1 to 2000 This parameter also affects the display parameter SPd1/SPd2/SPd3 in the SUP- menu (See Programming Manual)
3015	2000 / 10	bFr	R/WS	Standard motor frequency Factory setting: 0 0 = "50" 1 = "60" 50 Hz: IEC 60 Hz: NEMA This parameter modifies the presets of the following parameters: HSP page 23 , Ftd page 24 , FrS page 25 and tFr page 27 .
9601	2042 / 2	UnS	R/WS	Nominal motor voltage given on the rating plate Unit: 1 V Factory setting: According to drive rating Adjustment range according to drive rating: ATV31●●●M2: 100 to 240 V ATV31●●●M3X: 100 to 240 V ATV31●●●N4: 100 to 500 V ATV31●●●S6X: 100 to 600 V
9602	2042 / 3	FrS	R/WS	Nominal motor frequency given on the rating plate Unit: 0.1 Hz Factory setting: if bFr = 50: 500 if bFr = 60: 600 Adjustment range: 100 to 5000  The ratio $\frac{UnS \text{ (in volts)}}{FrS \text{ (in Hz)}}$ must not exceed the following values: ATV31●●●M2: 7 max. ATV31●●●M3X: 7 max. ATV31●●●N4: 14 max. ATV31●●●S6X: 17 max.
9603	2042 / 4	nCr	R/WS	Nominal motor current given on the rating plate Unit: 0.1 A Factory setting: According to drive rating Adjustment range: 0.25 to 1.5 In (1) (1) In corresponds to the nominal drive current indicated in the Installation Manual and on the drive rating plate.

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
9604	2042 / 5	nSP	R/WS	<p>Nominal motor speed given on the rating plate Unit: 1 rpm Factory setting: According to drive rating Adjustment range: 0 to 32767 RPM 0 to 9999 RPM then 10.00 to 32.76 KRPM If, rather than the nominal speed, the rating plate indicates the synchronous speed and the slip in Hz or as a %, calculate the nominal speed as follows:</p> $\text{Nominal speed} = \text{Synchronous speed} \times \frac{100 - \text{slip as a \%}}{100}$ <p>or</p> $\text{Nominal speed} = \text{Synchronous speed} \times \frac{50 - \text{slip in Hz}}{50} \quad (50 \text{ Hz motors})$ <p>or</p> $\text{Nominal speed} = \text{Synchronous speed} \times \frac{60 - \text{slip in Hz}}{60} \quad (60 \text{ Hz motors})$
9606	2042 / 7	COS	R/WS	<p>Motor Cos Phi given on the rating plate Unit: 0.01 Factory setting: According to drive rating Adjustment range: 50 to 100</p>
9643	2042 / 2C	rSC	R/WS	<p>Cold state stator resistance Factory setting: 0</p> <p>0 = "nO": Function inactive. For applications which do not require high performance or do not tolerate automatic auto-tuning (passing a current through the motor) each time the drive is powered up. 1 = "InIt": Activates the function. To improve low-speed performance whatever the thermal state of the motor. >1 = "XXXX" XXXX: Value of cold state stator resistance used, in mΩ. Caution: It is strongly recommended that this function is activated for Lifting and Handling applications. The function should be activated (InIt) only when the motor is in cold state. When rSC = InIt, parameter tUn is forced to POn. At the next run command or the next power-up, the stator resistance is measured with an auto-tune. Parameter rSC then changes to this value (XXXX) and maintains it; tUn remains forced to POn. Parameter rSC remains at InIt as long as the measurement has not been performed. Value XXXX can be forced or changed using the ▲ ▼ keys. XXXX corresponds to half the resistance measured between 2 phases.</p>
9608	2042 / 9	tUn	R/WO	<p>Motor control auto-tuning Factory setting: 0 It is essential that all the motor parameters (UnS, FrS, nCr, nSP, COS) are correctly configured before performing the auto-tuning.</p> <p>0 = "nO": Auto-tuning not performed. 112 = "YES": Auto-tuning is performed as soon as possible, then the parameter automatically switches to dOnE or nO in the event of a fault (the tnF fault is displayed if tnL = YES, see page 48). 113 = "dOnE": Use of the values given the last time auto-tuning was performed. 114 = "rUn": Auto-tuning is performed every time a run command is sent. 115 = "POn": Auto-tuning is performed on every power-up. 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6</p> <p>LI1 to LI6: Auto-tuning is performed on the transition from 0 → 1 of a logic input assigned to this function. Caution: tUn is forced to POn if rSC is other than nO. Auto-tuning is only performed if no command has been activated. If a "freewheel stop" or "fast stop" function has been assigned to a logic input, this input must be set to 1 (active at 0). Auto-tuning may last for 1 to 2 seconds. Do not interrupt; wait for the display to change to "dOnE" or "nO".</p> <p> During auto-tuning the motor operates at nominal current.</p>

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
9609	2042 / A	tUS	R	Auto-tuning status Factory setting: 0 0 = "tAb": The default stator resistance value is used to control the motor. 1 = "PEnd": Auto-tuning has been requested but not yet performed. 2 = "PrOG": Auto-tuning in progress. 3 = "FAIL": Auto-tuning has failed. 4 = "dOnE": The stator resistance measured by the auto-tuning function is used to control the motor. 5 = "Strd": The cold state stator resistance (rSC other than nO) is used to control the motor.
9607	2042 / 8	UFt	R/WS	Selection of the type of voltage/frequency ratio Factory setting: 2 0 = "L": Constant torque for motors connected in parallel or special motors 1 = "P": Variable torque for pump and fan applications 2 = "n": Sensorless flux vector control for constant torque applications 3 = "nLd": Energy saving, for variable torque applications not requiring high dynamics (behaves in a similar way to the P ratio at no load and the n ratio on load).
3107	2001 / 8	nrd	R/WS	Random switching frequency Factory setting: 1 0 = "nO": Fixed frequency 1 = "YES": Frequency with random modulation Random frequency modulation prevents any resonance which may occur at a fixed frequency.
3102	2001 / 3	SFr	R/W	Switching frequency Unit: 0.1 kHz Factory setting: 40 Adjustment range: 20 to 160 The frequency can be adjusted to reduce the noise generated by the motor. If the frequency has been set to a value higher than 4 kHz, in the event of excessive temperature rise, the drive will automatically reduce the switching frequency and increase it again once the temperature has returned to normal.
3103	2001 / 4	tFr	R/WS	Maximum output frequency Unit: 0.1 Hz Factory setting: if BFR = 50: 600 if BFR = 60: 720 Adjustment range: 100 to 5000
9101	203D / 2	SrF	R/WS	Suppression of the speed loop filter Factory setting: 0 0 = "nO": The speed loop filter is active (prevents the reference being exceeded). 1 = "YES": The speed loop filter is suppressed (in position control applications, this reduces the response time and the reference may be exceeded).
8001	2032 / 2	SCS	R/WS	Saving the configuration Factory setting: 0 0 = "nO": Function inactive 2 = "Str1": Saves the current configuration (but not the result of auto-tuning) to EEPROM. SCS automatically switches to nO as soon as the save has been performed. This function is used to keep another configuration in reserve, in addition to the current configuration. When drives leave the factory the current configuration and the backup configuration are both initialized with the factory configuration. If the remote display terminal option is connected to the drive, the following additional selection options will appear: 11 = "FIL1" 12 = "FIL2" 13 = "FIL3" 14 = "FIL4" FIL1, FIL2, FIL3, FIL4 are files available in the remote display terminal's EEPROM memory for saving the current configuration. They can be used to store between 1 and 4 different configurations which can also be stored on or even transferred to other drives of the same rating. SCS automatically switches to nO as soon as the save has been performed.

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
8002	2032 / 3	FCS	R/WS	<p>Return to factory settings/Restore configuration Factory setting: 0 0 = "nO": Function inactive 2 = "rEC1": The current configuration becomes identical to the backup configuration previously saved by SCS = Strl. rECI is only visible if the backup has been carried out. FCS automatically changes to nO as soon as this action has been performed. 64 = "InI": The current configuration becomes identical to the factory setting. FCS automatically changes to nO as soon as this action has been performed.</p> <p>If the remote display terminal option is connected to the drive, the following additional selection options appear, as long as the corresponding files have been loaded in the remote display terminal's EEPROM memory (0 to 4 files): 11 = "FIL1": display terminal file 1 not empty 12 = "FIL2": display terminal file 2 not empty 13 = "FIL3": display terminal file 3 not empty 14 = "FIL4": display terminal file 4 not empty They enable the current configuration to be replaced with one of the 4 configurations that may be loaded on the remote display terminal. FCS automatically changes to nO as soon as this action has been performed.</p>
11101	2051 / 2	tCC	R/WS	<p>2-wire/3-wire control (Type of control) Factory setting: 0 except for ATV31●●●A: 2 Control configuration: 0 = "2C" = 2-wire control: The open or closed state of the input controls running or stopping. 1 = "3C" = 3-wire control (pulse control): A "forward" or "reverse" pulse is sufficient to control starting, a "stop" pulse is sufficient to control stopping. 2 = "LOC" = local control (drive RUN/STOP/RESET) for ATV31●●●A only (inactive if LAC = L3, see page 30).</p> <p> Changing the assignment of tCC returns the following functions to their factory setting: rrS, tCt and all functions affecting logic inputs.</p>
11102	2051 / 3	tCt	R/WS	<p>Type of 2-wire control (parameter active only if tCC = 2C) Factory setting: 1 0 = "LEL": State 0 or 1 is taken into account for run or stop. 1 = "trn": A change of state (transition or edge) is necessary to initiate operation, in order to prevent accidental restarts after a break in the power supply. 2 = "PFO": State 0 or 1 is taken into account for run or stop, but the "forward" input always takes priority over the "reverse" input.</p>
11105	2051 / 6	rrS	R/WS	<p>Reverse operation via logic input Factory setting: - if tCC = 0: 130 - if tCC = 1: 131 - if tCC = 2: 0</p> <p>If rrS = nO, reverse operation is active, by means of negative voltage on AI2 for example. 0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6</p>
4434	200E / 23	CrL3	R/WS	<p>Value for low speed (LSP) on input AI3 Unit: 0.1 mA Factory setting: 40 Adjustment range: 0 to 200 CrL3 and CrH3 are used to configure the input for 0-20 mA, 4-20 mA, 20-4 mA, etc.</p>
4444	200E / 2D	CrH3	R/WS	<p>Value for high speed (HSP) on input AI3 Unit: 0.1 mA Factory setting: 200 Adjustment range: 40 to 200 CrL3 and CrH3 are used to configure the input for 0-20 mA, 4-20 mA, 20-4 mA, etc.</p>
4601	2010 / 2	AO1t	R/WS	<p>Configuration of the analog output Factory setting: 2 1 = "10U": 0 - 10 V configuration (use terminal AOV) 2 = "0A": 0 - 20 mA configuration (use terminal AOC) 3 = "4A": 4 - 20 mA configuration (use terminal AOC)</p>

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
5031	2014 / 20	dO	R/WS	<p>Analog/logic output AOC/AOV Factory setting: 0 0 = "nO": Not assigned For the following assignments the output is analog type: 129 = "OCr": Motor current. 20 mA or 10 V corresponds to twice the nominal drive current. 130 = "OFr": Motor frequency. 20 mA or 10 V corresponds to the maximum frequency tFr (page 27). 132 = "Otr": Motor torque. 20 mA or 10 V corresponds to twice the nominal motor torque. 139 = "OPr": Power supplied by the drive. 20 mA or 10 V corresponds to twice the nominal drive power.</p> <p>For the following assignments the output is logic type (see diagram in the Installation Manual):</p> <p> With these assignments, configure AO1t = 0A.</p> <p>1 = "FLt": Drive fault 2 = "rUn": Drive running 4 = "FtA": Frequency threshold reached (Ftd parameter page 24) 5 = "FLA": High speed (HSP) reached 6 = "CtA": Current threshold reached (Ctd parameter page 24) 7 = "SrA": Frequency reference reached 8 = "tSA": Motor thermal threshold reached (ttd parameter page 24) 9 = "bLC": Brake sequence (for information, as this assignment can be only be activated or deactivated via the bLC parameter page 42) 12 = "APL": Loss of 4-20 mA signal, even if LFL = nO (page 48) The logic output is in state 1 (24 V) when the selected assignment is active, with the exception of FLt (state 1 if the drive is not faulty).</p>
5001	2014 / 2	r1	R/WS	<p>Relay r1 Factory setting: 1 0 = "nO": Not assigned 1 = "FLt": Drive fault 2 = "rUn": Drive running 4 = "FtA": Frequency threshold reached (Ftd parameter page 24) 5 = "FLA": High speed (HSP) reached 6 = "CtA": Current threshold reached (Ctd parameter page 24) 7 = "SrA": Frequency reference reached 8 = "tSA": Motor thermal threshold reached (ttd parameter page 24) 12 = "APL": Loss of 4-20 mA signal, even if LFL = nO (page 48) The relay is powered up when the selected assignment is active, with the exception of FLt (powered up if the drive is not faulty).</p>
5002	2014 / 3	r2	R/WS	<p>Relay r2 Factory setting: 0 0 = "nO": Not assigned 1 = "FLt": Drive fault 2 = "rUn": Drive running 4 = "FtA": Frequency threshold reached (Ftd parameter page 24) 5 = "FLA": High speed (HSP) reached 6 = "CtA": Current threshold reached (Ctd parameter page 24) 7 = "SrA": Frequency reference reached 8 = "tSA": Motor thermal threshold reached (ttd parameter page 24) 9 = "bLC": Brake sequence (for information, as this assignment can be only be activated or deactivated via the bLC parameter page 42) 12 = "APL": Loss of 4-20 mA signal, even if LFL = nO (page 48) The relay is powered up when the selected assignment is active, with the exception of FLt (powered up if the drive is not faulty).</p>

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
3006	2000 / 7	LAC	R/WS	<p>Function access level Factory setting: 0 0 = "L1": Access to standard functions. Significantly, this level is interchangeable with ATV28. 1 = "L2": Access to advanced functions: - +/- speed (motorized potentiometer) - Brake control - Switching for second current limit - Motor switching - Management of limit switches 2 = L3: Access to advanced functions and management of mixed control modes.</p> <p> Assigning LAC to L3 will restore the factory settings of the Fr1 (below), Cd1 (page 31), CHCF (page 31), and tCC (page 28) parameters. The latter is forced to "2C" on ATV31●●●A. L3 can only be restored to L2 or L1 and L2 to L1 by means of a "factory setting" via FCS (page 28).</p>
8413	2036 / E	Fr1	R/WS	<p>Configuration reference 1 Factory setting: 1 except for ATV31●●●●A: 16 1 = "AI1": Analog input AI1 2 = "AI2": Analog input AI2 3 = "AI3": Analog input AI3 16 = "AIP": Potentiometer (ATV31●●●A only)</p> <p>If LAC = L2 or L3, the following additional assignments are possible: 160 = "UPdt": (1) + speed/- speed via LI 161 = "UpdH": (1) + speed/- speed via keys ▲ ▼ on the ATV31 or ATV31●●●A keypad or remote display terminal. For operation, display the frequency rFr (see page 16)</p> <p>If LAC = L3, the following additional assignments are possible: 163 = "LCC": Reference via the remote display terminal, LFr parameter page 14. 164 = "Mdb": Reference via Modbus 167 = "CAN": Reference via CANopen (1) Caution, you cannot assign UPdt to Fr1 or Fr2 and UPdH to Fr1 or Fr2 at the same time. Only one of the UPdt/UPdH assignments is permitted on each reference channel.</p>
8414	2036 / F	Fr2	R/WS	<p>Configuration reference 2 Factory setting: 0 0 = "nO": Not assigned 1 = "AI1": Analog input AI1 2 = "AI2": Analog input AI2 3 = "AI3": Analog input AI3 16 = "AIP": Potentiometer (ATV31●●●A only)</p> <p>If LAC = L2 or L3, the following additional assignments are possible: 160 = "UPdt": (1) + speed/- speed via LI 161 = "UpdH": (1) + speed/- speed via keys ▲ ▼ on the ATV31 or ATV31●●●A keypad or remote display terminal. For operation, display the frequency rFr (see page 16)</p> <p>If LAC = L3, the following additional assignments are possible: 163 = "LCC": Reference via the remote display terminal, LFr parameter page 14. 164 = "Mdb": Reference via Modbus 167 = "CAN": Reference via CANopen (1) Caution, you cannot assign UPdt to Fr1 or Fr2 and UPdH to Fr1 or Fr2 at the same time. Only one of the UPdt/UPdH assignments is permitted on each reference channel.</p>

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
8411	2036 / C	rFC	R/WS	<p>Reference switching Factory setting: 96 Parameter rFC can be used to select channel Fr1 or Fr2 or to configure a logic input or a control bit for remote switching of Fr1 or Fr2. 96 = "Fr1": Reference = Reference 1 97 = "Fr2": Reference = Reference 2 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6</p> <p>If LAC = L3, the following additional assignments are possible:</p> <p>187 = "C111": bit 11 of the CMD control word (page 14) written by Modbus 188 = "C112": bit 12 of the CMD control word (page 14) written by Modbus 189 = "C113": bit 13 of the CMD control word (page 14) written by Modbus 190 = "C114": bit 14 of the CMD control word (page 14) written by Modbus 191 = "C115": bit 15 of the CMD control word (page 14) written by Modbus 203 = "C211": bit 11 of the CMD control word (page 14) written by CANopen 205 = "C213": bit 13 of the CMD control word (page 14) written by CANopen 206 = "C214": bit 14 of the CMD control word (page 14) written by CANopen 207 = "C215": bit 15 of the CMD control word (page 14) written by CANopen</p> <p>The reference can be switched with the drive running. Fr1 is active when the logic input or control word bit is at state 0. Fr2 is active when the logic input or control word bit is at state 1.</p> <p> Switching channel may result in a change of direction of motor rotation.</p>
8401	2036 / 2	CHCF	R/WS	<p>Mixed mode (control channels separated from reference channels) Factory setting: 1 Active if LAC = L3 1 = "SIM": Combined 2 = "SEP": Separate</p>
8423	2036 / 18	Cd1	R/WS	<p>Configuration of control channel 1 Factory setting: 1 except for ATV31●●●A: 2 Active if CHCF = SEP and LAC = L3 1 = "tEr": Terminal block control 2 = "LOC": Keypad control (ATV31●●●A only) 3 = "LCC": Remote display terminal control 10 = "Mdb": Control via Modbus 20 = "CAn": Control via CAN</p>
8424	2036 / 19	Cd2	R/WS	<p>Configuration of control channel 2 Factory setting: 10 Active if CHCF = SEP and LAC = L3 1 = "tEr": Terminal block control 2 = "LOC": Keypad control (ATV31●●●A only) 3 = "LCC": Remote display terminal control 10 = "Mdb": Control via Modbus 20 = "CAn": Control via CAN</p>

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
8421	2036 / 16	CCS	R/WS	<p>Control channel switching Factory setting: 98 Active if CHCF = SEP and LAC = L3 Parameter CCS can be used to select channel Cd1 or Cd2 or to configure a logic input or a control bit for remote switching of Cd1 or Cd2. 98 = "Cd1": Control channel = Channel 1 99 = "Cd2": Control channel = Channel 2 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6 187 = "C111": bit 11 of the CMD control word (page 14) written by Modbus 188 = "C112": bit 12 of the CMD control word (page 14) written by Modbus 189 = "C113": bit 13 of the CMD control word (page 14) written by Modbus 190 = "C114": bit 14 of the CMD control word (page 14) written by Modbus 191 = "C115": bit 15 of the CMD control word (page 14) written by Modbus 203 = "C211": bit 11 of the CMD control word (page 14) written by CANopen 204 = "C212": bit 12 of the CMD control word (page 14) written by CANopen 205 = "C213": bit 13 of the CMD control word (page 14) written by CANopen 206 = "C214": bit 14 of the CMD control word (page 14) written by CANopen 207 = "C215": bit 15 of the CMD control word (page 14) written by CANopen</p> <p>Channel 1 is active when the input or control word bit is at state 0. Channel 2 is active when the input or control word bit is at state 1.</p> <p> Switching channel may result in a change of direction of motor rotation.</p>
8402	2036 / 3	COP	R/WS	<p>Copy channel 1 to channel 2 Factory setting: 0 Active if LAC = L3 Copying is only performed from channel 1 to channel 2. 0 = "nO": No copy 1 = "SP": Copy reference 2 = "Cd": Copy control 3 = "ALL": Copy control and reference</p> <p>Exceptions:</p> <ul style="list-style-type: none"> • If channel 2 is controlled via the terminal block (2-wire or 3-wire control), channel 1 control is not copied. • If channel 2 reference is set via analog input (AI1, AI2, AI3 or AIP), channel 1 reference is not copied. <p>Reference copied:</p> <ul style="list-style-type: none"> • If channel 2 is the +/- speed type, the output frequency applied to the motor (rFr) is copied. • In other cases (built-in keypad, remote display terminal or communication bus), the reference before ramp (FrH) is copied. <p>Note: If channel 2 is a communication bus, the copy is "overwritten" as soon as a new control or reference is received by the bus.</p>
64003	2262 / 4	LCC	R/WS	<p>Control via remote display terminal Factory setting: 0 Parameter active only with the remote display terminal option and if LAC = L1 or L2. 0 = "nO": Function inactive 1 = "YES": Enables control of the drive using the STOP/RESET, RUN and FWD/REV buttons on the display terminal. The speed reference is then given by parameter LFr page 14. Only the freewheel, fast stop and DC injection stop commands remain active on the terminal block. If the drive/terminal connection is cut or if the terminal has not been connected, the drive locks in an SLF fault.</p>
64002	2262 / 3	PSt	R/WS	<p>Stop priority Factory setting: 1 This function gives priority to the STOP key on the keypad (ATV31●●●A only) or the STOP key on the remote display terminal, regardless of the control channel (terminal block or communication bus). 0 = "nO": Function inactive 1 = "YES": STOP key priority</p>

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
64001	2262 / 2	rOt	R/WS	Direction of operation authorized Factory setting: 0 Direction of operation authorized for the RUN key on the keypad (ATV31●●●A only) or the RUN key on the remote display terminal. 0 = "dFr": Forward 1 = "drS": Reverse 2 = "bOt": Both directions are authorized (except for the keypad on the ATV31●●●A: Forward only).
9004	203C / 5	rPt	R/WS	Type of ramp Defines the shape of the acceleration and deceleration ramps. Factory setting: 0 0 = "LIn": Linear 1 = "S": S ramp 2 = "U": U ramp 3 = "CUS": Customized
9005	203C / 6	tA1	R/W	Start of CUS-type acceleration ramp rounded Unit: 1% (as % of total ramp time ACC or AC2) Factory setting: 10 Adjustment range: 0 to 100
9006	203C / 7	tA2	R/W	End of CUS-type acceleration ramp rounded Unit: 1% (as % of total ramp time ACC or AC2) Factory setting: 10 Adjustment range: 0 to 100 - tA1
9007	203C / 8	tA3	R/W	Start of CUS-type deceleration ramp rounded Unit: 1% (as % of total ramp time dEC or dE2) Factory setting: 10 Adjustment range: 0 to 100
9008	203C / 9	tA4	R/W	End of CUS-type deceleration ramp rounded Unit: 1% (as % of total ramp time dEC or dE2) Factory setting: 10 Adjustment range: 0 to 100 - tA3
9001	203C / 2	ACC	R/W	Acceleration ramp time Unit: 0.1 s Factory setting: 30 Adjustment range: 1 to 9999 Defined for accelerating between 0 and the nominal frequency FrS (page 25).
9002	203C / 3	dEC	R/W	Deceleration ramp time Unit: 0.1 s Factory setting: 30 Adjustment range: 1 to 9999 Defined for decelerating between the nominal frequency FrS (page 25) and 0. Check that the value of dEC is not too low in relation to the load to be stopped.
9010	203C / B	rPS	R/WS	Ramp switching Factory setting: 0 This function remains active regardless of the control channel. 0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6 If LAC = L3, the following assignments are possible: 171 = "Cd11": bit 11 of the CMD control word (page 14) written by Modbus or CANopen 172 = "Cd12": bit 12 of the CMD control word (page 14) written by Modbus or CANopen 173 = "Cd13": bit 13 of the CMD control word (page 14) written by Modbus or CANopen 174 = "Cd14": bit 14 of the CMD control word (page 14) written by Modbus or CANopen 175 = "Cd15": bit 15 of the CMD control word (page 14) written by Modbus or CANopen ACC and dEC are enabled when the logic input or control word bit is at state 0. AC2 and dE2 are enabled when the logic input or control word bit is at state 1.

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values															
9011	203C / C	FrT	R/WS	<p>Ramp switching threshold Unit: 0.1 Hz Factory setting: 0 Adjustment range: 0 to 5000 The second ramp is switched if the value of Frt is not equal to 0 (0 deactivates the function) and the output frequency is greater than Frt. Threshold ramp switching can be combined with switching via LI or bit as follows:</p> <table border="1"> <thead> <tr> <th>LI or bit</th> <th>Frequency</th> <th>Ramp</th> </tr> </thead> <tbody> <tr> <td>0</td> <td><FrT</td> <td>ACC, dEC</td> </tr> <tr> <td>0</td> <td>>FrT</td> <td>AC2, dE2</td> </tr> <tr> <td>1</td> <td><FrT</td> <td>AC2, dE2</td> </tr> <tr> <td>1</td> <td>>FrT</td> <td>AC2, dE2</td> </tr> </tbody> </table>	LI or bit	Frequency	Ramp	0	<FrT	ACC, dEC	0	>FrT	AC2, dE2	1	<FrT	AC2, dE2	1	>FrT	AC2, dE2
LI or bit	Frequency	Ramp																	
0	<FrT	ACC, dEC																	
0	>FrT	AC2, dE2																	
1	<FrT	AC2, dE2																	
1	>FrT	AC2, dE2																	
9012	203C / D	AC2	R/W	<p>2nd acceleration ramp time Unit: 0.1 s Factory setting: 50 Adjustment range: 1 to 9999 Enabled via logic input (rPS) or frequency threshold (FrT).</p>															
9013	203C / E	dE2	R/W	<p>2nd deceleration ramp time Unit: 0.1 s Factory setting: 50 Adjustment range: 1 to 9999 Enabled via logic input (rPS) or frequency threshold (FrT).</p>															
9003	203C / 4	brA	R/WS	<p>Deceleration ramp adaptation Factory setting: 1 Activating this function automatically adapts the deceleration ramp, if this has been set at too low a value for the inertia of the load. 0 = "nO": Function inactive 1 = "YES": Function active. The function is incompatible with applications requiring: - positioning on a ramp - the use of a braking resistor (no guarantee of the function operating correctly) brA is forced to nO if brake control bLC is assigned (page 42).</p>															
11201	2052 / 2	Stt	R/WS	<p>Normal stop mode Factory setting: 0 Stop mode on disappearance of the run command or appearance of a stop command. 0 = "rMP": On ramp 1 = "FSt": Fast stop 2 = "nSt": Freewheel stop 3 = "dCI": DC injection stop</p>															
11204	2052 / 5	FSt	R/WS	<p>Fast stop via logic input Factory setting: 0 0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6</p> <p>If LAC = L3, the following assignments are possible:</p> <p>171 = "Cd11": bit 11 of the CMD control word (page 14) written by Modbus or CANopen 172 = "Cd12": bit 12 of the CMD control word (page 14) written by Modbus or CANopen 173 = "Cd13": bit 13 of the CMD control word (page 14) written by Modbus or CANopen 174 = "Cd14": bit 14 of the CMD control word (page 14) written by Modbus or CANopen 175 = "Cd15": bit 15 of the CMD control word (page 14) written by Modbus or CANopen</p> <p>The stop is activated when the logic state of the input changes to 0 and the control word bit changes to 1. The fast stop is a stop on a reduced ramp via parameter dCF. If the input falls back to state 1 and the run command is still active, the motor will only restart if 2-wire level control has been configured (tCC = 2C and tCt = LEL or PFO, see page 28). In other cases, a new run command must be sent.</p>															

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
11230	2052 / 1F	dCF	R/WS	Coefficient for dividing the deceleration ramp time for fast stopping Unit: 1 Factory setting: 4 Adjustment range: 0 to 10 Ensure that the reduced ramp is not too low in relation to the load to be stopped. The value 0 corresponds to the minimum ramp.
11203	2052 / 4	dCI	R/WS	DC injection via logic input Factory setting: 0 0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6 If LAC = L3, the following assignments are possible: 171 = "Cd11": bit 11 of the CMD control word (page 14) written by Modbus or CANopen 172 = "Cd12": bit 12 of the CMD control word (page 14) written by Modbus or CANopen 173 = "Cd13": bit 13 of the CMD control word (page 14) written by Modbus or CANopen 174 = "Cd14": bit 14 of the CMD control word (page 14) written by Modbus or CANopen 175 = "Cd15": bit 15 of the CMD control word (page 14) written by Modbus or CANopen Braking is activated when the logic state of the input or control word bit is at 1.
11210	2052 / B	IdC	R/W	Level of DC injection braking current activated via logic input or selected as stop mode Caution: This setting is not related to the "automatic standstill DC injection" function. Unit: 0.1 A Factory setting: 0.7 In (1) Adjustment range: 0 to In (1) After 5 seconds the injection current is peak limited at 0.5 Ith if it is set at a higher value. (1) In corresponds to the nominal drive current indicated in the Installation Manual and on the drive rating plate.
11211	2052 / C	tdC	R/W	Total DC injection braking time selected as normal stop mode Caution: This setting is not related to the "automatic standstill DC injection" function. Unit: 0.1 s Factory setting: 5 Adjustment range: 1 to 300
11202	2052 / 3	nSt	R/WS	Freewheel stop via logic input Factory setting: 0 0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6 The stop is activated when the logic state of the input is at 0. If the input falls back to state 1 and the run command is still active, the motor will only restart if 2-wire level control has been configured. In other cases, a new run command must be sent.
10401	204A / 2	AdC	R/W	Automatic standstill DC injection (at the end of the ramp) Factory setting: 1 0 = "nO": No injection 1 = "YES": Standstill injection for adjustable period 2 = "Ct": Continuous standstill injection  This parameter gives rise to the injection of current even if a run command has not been sent.

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
10402	204A / 3	tdC1	R/W	Automatic standstill DC injection time Unit: 0.1 s Factory setting: 50 Adjustment range: 1 to 300
10403	204A / 4	SdC1	R/W	Level of automatic standstill DC injection current Unit: 0.1 A Factory setting: 0.7 In (1) Adjustment range: 0 to 1.2 In (1)  Check that the motor will withstand this current without overheating. (1) In corresponds to the nominal drive current indicated in the Installation Manual and on the drive rating plate.
10404	204A / 5	tdC2	R/W	2nd automatic standstill DC injection time Unit: 0.1 s Factory setting: 0 Adjustment range: 0 to 300
10405	204A / 6	SdC2	R/W	2nd level of standstill DC injection current Unit: 0.1 A Factory setting: 0.5 In (1) Adjustment range: 0 to 1.2 In (1)  Check that the motor will withstand this current without overheating. (1) In corresponds to the nominal drive current indicated in the Installation Manual and on the drive rating plate.
11801	2058 / 2	SA2	R/WS	Summing input 2 Factory setting: 2 Can be used to sum one or two inputs to reference Fr1 only. 0 = "nO": Not assigned 1 = "AI1": Analog input AI1 2 = "AI2": Analog input AI2 3 = "AI3": Analog input AI3 16 = "AIP": Potentiometer (type A drives only) If LAC = L3, the following assignments are possible: 163 = "LCC": Reference via the remote display terminal, LFr parameter in the SET- menu page 14 . 164 = "Mdb": Reference via Modbus 167 = "CAN": Reference via CANopen
11802	2058 / 3	SA3	R/WS	Summing input 3 Factory setting: 0 Can be used to sum one or two inputs to reference Fr1 only. 0 = "nO": Not assigned 1 = "AI1": Analog input AI1 2 = "AI2": Analog input AI2 3 = "AI3": Analog input AI3 16 = "AIP": Potentiometer (type A drives only) If LAC = L3, the following assignments are possible: 163 = "LCC": Reference via the remote display terminal, LFr parameter in the SET- menu page 14 . 164 = "Mdb": Reference via Modbus 167 = "CAN": Reference via CANopen

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
11401	2054 / 2	PS2	R/WS	<p>2 preset speeds Factory setting: if tCC = 1: 0 if tCC = 0 or 2: 131 Selecting the assigned logic input activates the function. 0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6</p> <p>If LAC = L3, the following assignments are possible:</p> <p>171 = "Cd11": bit 11 of the CMD control word (page 14) written by Modbus or CANopen 172 = "Cd12": bit 12 of the CMD control word (page 14) written by Modbus or CANopen 173 = "Cd13": bit 13 of the CMD control word (page 14) written by Modbus or CANopen 174 = "Cd14": bit 14 of the CMD control word (page 14) written by Modbus or CANopen 175 = "Cd15": bit 15 of the CMD control word (page 14) written by Modbus or CANopen</p>
11402	2054 / 3	PS4	R/WS	<p>4 preset speeds Factory setting: if tCC = 1: 0 if tCC = 0 or 2: 132 Selecting the assigned logic input activates the function. Check that PS2 has been assigned before assigning PS4.</p> <p>0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6</p> <p>If LAC = L3, the following assignments are possible:</p> <p>171 = "Cd11": bit 11 of the CMD control word (page 14) written by Modbus or CANopen 172 = "Cd12": bit 12 of the CMD control word (page 14) written by Modbus or CANopen 173 = "Cd13": bit 13 of the CMD control word (page 14) written by Modbus or CANopen 174 = "Cd14": bit 14 of the CMD control word (page 14) written by Modbus or CANopen 175 = "Cd15": bit 15 of the CMD control word (page 14) written by Modbus or CANopen</p>
11403	2054 / 4	PS8	R/WS	<p>8 preset speeds Factory setting: 0 Selecting the assigned logic input activates the function. Check that PS4 has been assigned before assigning PS8.</p> <p>0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6</p> <p>If LAC = L3, the following assignments are possible:</p> <p>171 = "Cd11": bit 11 of the CMD control word (page 14) written by Modbus or CANopen 172 = "Cd12": bit 12 of the CMD control word (page 14) written by Modbus or CANopen 173 = "Cd13": bit 13 of the CMD control word (page 14) written by Modbus or CANopen 174 = "Cd14": bit 14 of the CMD control word (page 14) written by Modbus or CANopen 175 = "Cd15": bit 15 of the CMD control word (page 14) written by Modbus or CANopen</p>

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
11404	2054 / 5	PS16	R/WS	<p>16 preset speeds Factory setting: 0 Selecting the assigned logic input activates the function. Check that PS8 has been assigned before assigning PS16.</p> <p>0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6</p> <p>If LAC = L3, the following assignments are possible:</p> <p>171 = "Cd11": bit 11 of the CMD control word (page 14) written by Modbus or CANopen 172 = "Cd12": bit 12 of the CMD control word (page 14) written by Modbus or CANopen 173 = "Cd13": bit 13 of the CMD control word (page 14) written by Modbus or CANopen 174 = "Cd14": bit 14 of the CMD control word (page 14) written by Modbus or CANopen 175 = "Cd15": bit 15 of the CMD control word (page 14) written by Modbus or CANopen</p>
11410	2054 / B	SP2	R/W	<p>2nd preset speed Unit: 0.1 Hz Factory setting: 100 Adjustment range: 0 to 5000</p>
11411	2054 / C	SP3	R/W	<p>3rd preset speed Unit: 0.1 Hz Factory setting: 150 Adjustment range: 0 to 5000</p>
11412	2054 / D	SP4	R/W	<p>4th preset speed Unit: 0.1 Hz Factory setting: 200 Adjustment range: 0 to 5000</p>
11413	2054 / E	SP5	R/W	<p>5th preset speed Unit: 0.1 Hz Factory setting: 250 Adjustment range: 0 to 5000</p>
11414	2054 / F	SP6	R/W	<p>6th preset speed Unit: 0.1 Hz Factory setting: 300 Adjustment range: 0 to 5000</p>
11415	2054 / 10	SP7	R/W	<p>7th preset speed Unit: 0.1 Hz Factory setting: 350 Adjustment range: 0 to 5000</p>
11416	2054 / 11	SP8	R/W	<p>8th preset speed Unit: 0.1 Hz Factory setting: 400 Adjustment range: 0 to 5000</p>
11417	2054 / 12	SP9	R/W	<p>9th preset speed Unit: 0.1 Hz Factory setting: 450 Adjustment range: 0 to 5000</p>
11418	2054 / 13	SP10	R/W	<p>10th preset speed Unit: 0.1 Hz Factory setting: 500 Adjustment range: 0 to 5000</p>
11419	2054 / 14	SP11	R/W	<p>11th preset speed Unit: 0.1 Hz Factory setting: 550 Adjustment range: 0 to 5000</p>

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
11420	2054 / 15	SP12	R/W	12th preset speed Unit: 0.1 Hz Factory setting: 600 Adjustment range: 0 to 5000
11421	2054 / 16	SP13	R/W	13th preset speed Unit: 0.1 Hz Factory setting: 700 Adjustment range: 0 to 5000
11422	2054 / 17	SP14	R/W	14th preset speed Unit: 0.1 Hz Factory setting: 800 Adjustment range: 0 to 5000
11423	2054 / 18	SP15	R/W	15th preset speed Unit: 0.1 Hz Factory setting: 900 Adjustment range: 0 to 5000
11424	2054 / 19	SP16	R/W	16th preset speed Unit: 0.1 Hz Factory setting: 1000 Adjustment range: 0 to 5000
11110	2051 / B	JOG	R/WS	Jog operation Factory setting: if tCC = 0 or 2: 0 if tCC = 1: 132 Selecting the assigned logic input activates the function. 0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6
11111	2051 / C	JGF	R/W	Jog operation reference Unit: 0.1 Hz Factory setting: 100 Adjustment range: 0 to 100
11501	2055 / 2	USP	R/WS	+ speed (motorized potentiometer) Factory setting: 0 Function active only if LAC = L2 or L3 and UPdt has been selected (see page 30). Selecting the assigned logic input activates the function. 0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6
11502	2055 / 3	dSP	R/WS	- speed (motorized potentiometer) Factory setting: 0 Function active only if LAC = L2 or L3 and UPdt has been selected (see page 30). Selecting the assigned logic input activates the function. 0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
11503	2055 / 4	Str	R/WS	Save reference Factory setting: 0 Associated with the "+/- speed" function, this parameter can be used to save the reference: <ul style="list-style-type: none"> - When the run commands disappear (saved to RAM) - When the line supply or the run commands disappear (saved to EEPROM) On the next start-up, the speed reference is the last reference saved. 0 = "nO": No save 1 = "rAM": Save to RAM 2 = "EEP": Save to EEPROM
11901	2059 / 2	PIF	R/WS	PI regulator feedback Factory setting: 0 0 = "nO": Not assigned 1 = "AI1": Analog input AI1 2 = "AI2": Analog input AI2 3 = "AI3": Analog input AI3
11941	2059 / 2A	rPG	R/W	PI regulator proportional gain Unit: 0.01 Factory setting: 100 Adjustment range: 1 to 10000 Contributes to dynamic performance during rapid changes in the PI feedback.
11942	2059 / 2B	rIG	R/W	PI regulator integral gain Unit: 0.01 Factory setting: 100 Adjustment range: 1 to 10000 Contributes to static precision during slow changes in the PI feedback.
11903	2059 / 4	FbS	R/W	PI feedback multiplication coefficient Unit: 0.1 Factory setting: 10 Adjustment range: 1 to 1000 For process adaptation
11940	2059 / 29	PIC	R/W	Reversal of the direction of correction of the PI regulator Factory setting: 0 0 = "nO": normal 1 = "YES": reverse
11909	2059 / A	Pr2	R/WS	2 preset PI references Factory setting: 0 Selecting the assigned logic input activates the function. 0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6 If LAC = L3, the following assignments are possible: 171 = "Cd11": bit 11 of the CMD control word (page 14) written by Modbus or CANopen 172 = "Cd12": bit 12 of the CMD control word (page 14) written by Modbus or CANopen 173 = "Cd13": bit 13 of the CMD control word (page 14) written by Modbus or CANopen 174 = "Cd14": bit 14 of the CMD control word (page 14) written by Modbus or CANopen 175 = "Cd15": bit 15 of the CMD control word (page 14) written by Modbus or CANopen

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
11910	2059 / B	rP4	R/WS	<p>4th preset PI references Factory setting: 0 Selecting the assigned logic input activates the function. Check that Pr2 has been assigned before assigning Pr4.</p> <p>0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6</p> <p>If LAC = L3, the following assignments are possible:</p> <p>171 = "Cd11": bit 11 of the CMD control word (page 14) written by Modbus or CANopen 172 = "Cd12": bit 12 of the CMD control word (page 14) written by Modbus or CANopen 173 = "Cd13": bit 13 of the CMD control word (page 14) written by Modbus or CANopen 174 = "Cd14": bit 14 of the CMD control word (page 14) written by Modbus or CANopen 175 = "Cd15": bit 15 of the CMD control word (page 14) written by Modbus or CANopen</p>
11921	2059 / 16	rP2	R/W	<p>2nd preset PI reference Unit: 0.1% Factory setting: 300 Adjustment range: 0 to 1000 Only active if Pr2 has been enabled by selecting an input.</p>
11922	2059 / 17	rP3	R/W	<p>3rd preset PI reference Unit: 0.1% Factory setting: 600 Adjustment range: 0 to 1000 Only active if Pr4 has been enabled by selecting an input.</p>
11923	2059 / 18	rP4	R/W	<p>4th preset PI reference Unit: 0.1% Factory setting: 900 Adjustment range: 0 to 1000 Only active if Pr4 has been enabled by selecting an input.</p>
11960	2059 / 3D	rSL	RW0	<p>Restart error threshold ("wake-up" threshold) Unit: 0.1 Factory setting: 0 Adjustment range: 0 to 1000 If the "PI" and "Low speed operating time"(tLS) (see page 24) functions are configured at the same time, the PI regulator may attempt to set a speed lower than LSP. This results in unsatisfactory operation which consists of starting, operating at low speed then stopping, and so on... Parameter rSL (restart error threshold) can be used to set a minimum PI error threshold for restarting after a stop at prolonged LSP. The function is inactive if tLS = 0.</p>
11908	2059 / 9	PII	R/WS	<p>Internal PI regulator reference Factory setting: 0 0 = "nO": The PI regulator reference is Fr1, except for UPdH and UPdt (+/- speed cannot be used as the PI regulator reference). 1 = "YES": The PI regulator reference is internal via parameter rPI.</p>
11920	2059 / 15	rPI	R/W	<p>Internal PI regulator reference Unit: 0.1% Factory setting: 0 Adjustment range: 0 to 1000</p>

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
10001	2046 / 2	bLC	R/WS	Brake control configuration Factory setting: 0 Function active only if LAC = L2 or L3 (page 30). 0 = "nO": Not assigned 2 = "r2": Relay R2 64 = "dO": Logic output AOC If bLC is assigned, parameters FLr (page 46) and brA (page 34) are forced to nO, and parameter OPL (page 47) is forced to YES. bLC is forced to nO if OPL = OAC (page 46).
10002	2046 / 3	brL	R/WS	Brake release frequency Unit: 0.1 Hz Factory setting: According to drive rating Adjustment range: 0 to 100
10006	2046 / 7	lbr	R/WS	Motor current threshold for brake release Unit: 0.1 A Factory setting: According to drive rating Adjustment range: 0 to 1.36 In (1) (1) In corresponds to the nominal drive current indicated in the Installation Manual and on the drive rating plate.
10004	2046 / 5	brt	R/WS	Brake release time Unit: 0.01 s Factory setting: 50 Adjustment range: 0 to 500
10003	2046 / 4	bEn	R/WS	Brake engage frequency threshold Unit: 0.1 Hz Factory setting: 65535 Adjustment range: 0 to LSP 65535 = "nO": Not set 0 to LSP: Adjustment range in Hz If bLC is assigned and bEn still equals nO, the drive will lock on a bLF fault on the first run command.
10005	2046 / 6	bEt	R/WS	Brake engage time Unit: 0.01 s Factory setting: 50 Adjustment range: 0 to 500
10007	2046 / 8	bIP	R/WS	Brake release pulse Factory setting: 0 0 = "nO": Whilst the brake is releasing, the motor torque direction corresponds to the direction of rotation commanded. 1 = "YES": Whilst the brake is releasing, the motor torque direction is always forward, regardless of the direction of operation commanded.  Check that the motor torque direction for "Forward" control corresponds to the upward direction of the load. If necessary, reverse two motor phases.

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
9202	203E / 3	LC2	R/WS	<p>Switching for second current limit Factory setting: 0 Function active only if LAC = L2 or L3 (page 30). Selecting the assigned logic input activates the function. 0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6</p> <p>If LAC = L3, the following assignments are possible:</p> <p>171 = "Cd11": bit 11 of the CMD control word (page 14) written by Modbus or CANopen 172 = "Cd12": bit 12 of the CMD control word (page 14) written by Modbus or CANopen 173 = "Cd13": bit 13 of the CMD control word (page 14) written by Modbus or CANopen 174 = "Cd14": bit 14 of the CMD control word (page 14) written by Modbus or CANopen 175 = "Cd15": bit 15 of the CMD control word (page 14) written by Modbus or CANopen CL1 is enabled when the logic input or control word bit is at state 0 (page 24). CL2 is enabled when the logic input or control word bit is at state 1 (page 43).</p>
9203	203E / 4	CL2	R/W	<p>2nd current limit Unit: 0.1 A Factory setting: 1.5 In (1) Adjustment range: 0.25 to 1.5 In (1) (1) In corresponds to the nominal drive current indicated in the Installation Manual and on the drive rating plate.</p>
8011	2032 / C	CHP	R/WS	<p>Switching, motor 2 Factory setting: 0 Function active only if LAC = L2 or L3 (page 30). 0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6</p> <p>If LAC = L3, the following assignments are possible:</p> <p>171 = "Cd11": bit 11 of the CMD control word (page 14) written by Modbus or CANopen 172 = "Cd12": bit 12 of the CMD control word (page 14) written by Modbus or CANopen 173 = "Cd13": bit 13 of the CMD control word (page 14) written by Modbus or CANopen 174 = "Cd14": bit 14 of the CMD control word (page 14) written by Modbus or CANopen 175 = "Cd15": bit 15 of the CMD control word (page 14) written by Modbus or CANopen</p> <p>LI or bit = 0: Motor 1 LI or bit = 1: Motor 2</p> <p> - The motor switching function disables motor thermal protection. An external means of motor thermal protection must therefore be provided. - If you use this function, do not use the tUn auto-tuning function (page 26) on motor 2 and do not configure tUn = rUn or POn. - Changes to parameters are only taken into account when the drive is locked.</p>
9701	2043 / 2	UnS2	R/WS	<p>Nominal motor voltage (motor 2) given on the rating plate Unit: 1 V Factory setting: According to drive rating Adjustment range: According to drive rating: ATV31●●●M2: 100 to 240 V ATV31●●●M3X: 100 to 240 V ATV31●●●N4: 100 to 500 V ATV31●●●S6X: 100 to 600 V</p>

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
9702	2043 / 3	FrS2	R/WS	<p>Nominal motor frequency (motor 2) given on the rating plate Unit: 0.1 Hz Factory setting: if bFr = 50: 500 if bFr = 60: 600 Adjustment range: 100 to 5000</p> <p> The ratio $\frac{UnS \text{ (in volts)}}{FrS \text{ (in Hz)}}$ must not exceed the following values: ATV31●●●M2: 7 max. ATV31●●●M3X: 7 max. ATV31●●●N4: 14 max. ATV31●●●S6X: 17 max.</p>
9703	2043 / 4	nCr2	R/WS	<p>Nominal motor current (motor 2) given on the rating plate Unit: 0.1 A Factory setting: According to drive rating Adjustment range: 0.25 to 1.5 In (1) (1) In corresponds to the nominal drive current indicated in the Installation Manual and on the drive rating plate.</p>
9704	2043 / 5	nSP2	R/WS	<p>Nominal motor speed (motor 2) given on the rating plate Unit: 1 rpm Factory setting: According to drive rating Adjustment range: 0 to 32767 If, rather than the nominal speed, the rating plate indicates the synchronous speed and the slip in Hz or as a %, calculate the nominal speed as follows:</p> <p>Nominal speed = Synchronous speed x $\frac{100 - \text{slip as a \%}}{100}$ or Nominal speed = Synchronous speed x $\frac{50 - \text{slip in Hz}}{50}$ (50 Hz motors) or Nominal speed = Synchronous speed x $\frac{60 - \text{slip in Hz}}{60}$ (60 Hz motors)</p>
9706	2043 / 7	COS2	R/WS	<p>Motor Cos Phi (motor 2) given on the rating plate Unit: 0.01 Factory setting: According to drive rating Adjustment range: 50 to 100</p>
9707	2043 / 8	UFt2	R/W	<p>Selection of the type of voltage/frequency ratio for motor 2 Factory setting: 2 0 = "L": Constant torque for motors connected in parallel or special motors 1 = "P": Variable torque for pump and fan applications 2 = "n": Sensorless flux vector control for constant torque applications 3 = "nLd": Energy saving, for variable torque applications not requiring high dynamics (behaves in a similar way to the P ratio at no load and the n ratio on load).</p>
9723	2043 / 18	UFr2	R/W	<p>IR compensation/Voltage boost, motor 2 Unit: 1% Factory setting: 20 Adjustment range: 0 to 100 For UFt2 = n or nLd: IR compensation. For UFt2 = L or P: Voltage boost. Used to optimize the torque at very low speed (increase UFr2 if the torque is insufficient). Check that the value of UFr2 is not too high for when the motor is warm (risk of instability). Modifying UFr2 will cause UFr2 to return to the factory setting (20%).</p>
9720	2043 / 15	FLG2	R/W	<p>Frequency loop gain, motor 2 Unit: 1% Factory setting: 20 Adjustment range: 1 to 100 Parameter active only if UFt2 = n or nLd. The FLG2 parameter adjusts the drive's ability to follow the speed ramp based on the inertia of the machine being driven. Too high a gain may result in operating instability.</p>

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
9721	2043 / 16	StA2	R/W	Frequency loop stability, motor 2 Unit: 1% Factory setting: 20 Adjustment range: 1 to 100 Parameter active only if UFt2 = n or nLd. Used to adapt the return to steady state after a speed transient (acceleration or deceleration), according to the dynamics of the machine. Gradually increase the stability to avoid any overspeed.
9725	2043 / 1A	SLP2	R/W	Slip compensation, motor 2 Unit: 1% Factory setting: 100 Adjustment range: 0 to 150 Parameter active only if UFt2 = n or nLd. Used to adjust the slip compensation value fixed by nominal motor speed. The speeds given on motor rating plates are not necessarily exact. If slip setting < actual slip: the motor is not rotating at the correct speed in steady state. If slip setting > actual slip: the motor is overcompensated and the speed is unstable.
11601	2056 / 2	LAF	R/WS	Limit, forward direction Factory setting: 0 Function active only if LAC = L2 or L3 (page 30). 0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6
11602	2056 / 3	LAr	R/WS	Limit, reverse direction Factory setting: 0 Function active only if LAC = L2 or L3 (page 30). 0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6
11603	2056 / 4	LAS	R/WS	Type of limit switch stop Factory setting: 2 Function active only if LAC = L2 or L3 (page 30). 0 = "rMP": On ramp 1 = "FSt": Fast stop 2 = "nSt": Freewheel stop

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
7122	2029 / 17	Atr	R/WS	<p>Automatic restart Factory setting: 0 0 = "nO": Function inactive 1 = "YES": Automatic restart, after locking on a fault, if the fault has disappeared and the other operating conditions permit the restart. The restart is performed by a series of automatic attempts separated by increasingly longer waiting periods: 1 s, 5 s, 10 s, then 1 min for the following periods. If the restart has not taken place once the configurable time tAr has elapsed, the procedure is aborted and the drive remains locked until it is powered down then powered up. The following faults permit this function:</p> <ul style="list-style-type: none"> - External fault (EPF) - Loss of 4-20 mA reference (LFF) - CANopen fault (COF) - Line overvoltage (OSF) - Loss of a line phase (PHF) - Loss of a motor phase (OPF) - DC bus overvoltage (ObF) - Motor overload (OLF) - Serial link (SLF) - Drive overheating (OHF) <p>The drive safety relay remains activated if this function is active. The speed reference and the operating direction must be maintained. Use 2-wire control (tCC = 2C) with tCt = LEL or PFO (page 28).</p> <p> Check that an automatic restart does not present any danger to personnel or equipment.</p>
7123	2029 / 18	tAr	R/WS	<p>Max. duration of restart process Factory setting: 0 0 = "5" : 5 minutes 1 = "10" : 10 minutes 2 = "30" : 30 minutes 3 = "1h" : 1 hour 4 = "2h" : 2 hours 5 = "3h" : 3 hours 6 = "Ct" : Unlimited This parameter is active if Atr = YES. It can be used to limit the number of consecutive restarts on a recurrent fault.</p>
7124	2029 / 19	rSF	R/WS	<p>Reset of current fault Factory setting: 0 0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6</p>
3110	2001 / B	FLr	R/WS	<p>Flying restart (automatic catching a spinning load on ramp) Factory setting: 0 Used to enable a smooth restart if the run command is maintained after the following events:</p> <ul style="list-style-type: none"> - Loss of line supply or disconnection - Reset of current fault or automatic restart - Freewheel stop <p>The speed given by the drive resumes from the estimated speed of the motor at the time of the restart, then follows the ramp to the reference speed. This function requires 2-wire control (tCC = 2C) with tCt = LEL or PFO. 0 = "nO": Function inactive 1 = "YES": Function active When the function is operational, it activates on each restart following one of the above events, resulting in a slight delay (1 second max). FLr is forced to nO if brake control (bLC) is assigned (page 42).</p>

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
7131	2029 / 20	EtF	R/WS	External fault Factory setting: 0 0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6 If LAC = L3, the following assignments are possible: 171 = "Cd11": bit 11 of the CMD control word (page 14) written by Modbus or CANopen 172 = "Cd12": bit 12 of the CMD control word (page 14) written by Modbus or CANopen 173 = "Cd13": bit 13 of the CMD control word (page 14) written by Modbus or CANopen 174 = "Cd14": bit 14 of the CMD control word (page 14) written by Modbus or CANopen 175 = "Cd15": bit 15 of the CMD control word (page 14) written by Modbus or CANopen
7006	2028 / 7	EPL	R/WS	Stop mode in the event of an external fault EPF Factory setting: 1 0 = "nO": Fault ignored 1 = "YES": Fault with freewheel stop 6 = "rMP": Fault with stop on ramp 7 = "FSt": Fault with fast stop
9611	2042 / C	OPL	R/WS	Configuration of motor phase loss fault Factory setting: 1 0 = "nO": Function inactive 1 = "YES": Triggering of OPF fault 2 = "OAC": No fault triggered but management of the output voltage in order to avoid an overcurrent when the link with the motor is re-established and flying restart even if FLr = nO. To be used with downstream contactor. OPL is forced to YES if brake control bLC is assigned (page 42). If OPL = OAC, bLC is forced to nO (page 42).
7002	2028 / 3	IPL	R/WS	Configuration of line phase loss fault Factory setting: 1 except for ATV31●●M2: 0 This parameter is only active on 3-phase drives. 0 = "nO": Fault ignored 1 = "YES": Fault with fast stop
7008	2028 / 9	OHL	R/WS	Stop mode in the event of a drive overheating fault OHF Factory setting: 1 0 = "nO": Fault ignored 1 = "YES": Fault with freewheel stop 6 = "rMP": Fault with stop on ramp 7 = "FSt": Fault with fast stop
7009	2028 / A	OLL	R/WS	Stop mode in the event of a motor overload fault OLF Factory setting: 1 0 = "nO": Fault ignored 1 = "YES": Fault with freewheel stop 6 = "rMP": Fault with stop on ramp 7 = "FSt": Fault with fast stop
7010	2028 / B	SLL	R/WS	Stop mode in the event of a Modbus serial link fault SLF Factory setting: 1 0 = "nO": Fault ignored 1 = "YES": Fault with freewheel stop 6 = "rMP": Fault with stop on ramp 7 = "FSt": Fault with fast stop
7011	2028 / C	COL	R/WS	Stop mode in the event of a CANopen serial link fault COF Factory setting: 1 0 = "nO": Fault ignored 1 = "YES": Fault with freewheel stop 6 = "rMP": Fault with stop on ramp 7 = "FSt": Fault with fast stop

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
7012	2028 / D	tnL	R/WS	Configuration of auto-tuning fault tnF Factory setting: 1 0 = "nO": Fault ignored (the drive reverts to the factory settings) 1 = "YES": Fault with drive locked. If rSC (see page 26) is other than nO, tnL is forced to YES.
7003	2028 / 4	LFL	R/WS	Stop mode in the event of a loss of 4 - 20 mA signal fault LFF Factory setting: 0 0 = "nO": Fault ignored (only value possible if CrL3 ≤ 3 mA, see page 28) 1 = "YES": Fault with freewheel stop 4 = "LFF": The drive switches to the fallback speed (LFF parameter) 5 = "rLS": The drive maintains the speed at which it was travelling when the fault occurred until the fault has disappeared. 6 = "rMP": Fault with stop on ramp 7 = "FSt": Fault with fast stop The factory setting of LFL is forced to YES if CrH3 < CrL3 (see page 28) and nO is impossible. Before setting LFL to YES, rMP or FSt, check the connection of input AI3. Otherwise,  the drive may immediately switch to an LFF fault.
7080	2028 / 51	LFF	R/WS	Fallback speed Unit: 0.1 Hz Factory setting: 100 Adjustment range: 0 to 5000 Fallback speed setting for stopping in the event of a fault
7007	2028 / 8	drn	R/WS	Derated operation in the event of an overvoltage Factory setting: 0 0 = "nO": Function inactive 1 = "YES": The line voltage monitoring threshold is: ATV31●●●M2: 130 V ATV31●●●M3X: 130 V ATV31●●●N4: 270 V ATV31●●●S6X: 340 V In this case, a line choke must be used and the performance of the drive cannot be guaranteed.
7004	2028 / 5	StP	R/WS	Controlled stop on mains power break Factory setting: 0 0 = "nO": Locking of the drive and freewheel stopping of the motor 1 = "MMS": This stop mode uses the inertia to maintain the drive power supply as long as possible. 2 = "rMP": Stop according to the valid ramp (dEC or dE2) 3 = "FSt": Fast stop, the stopping time depends on the inertia and the braking ability of the drive.
7125	2029 / 1A	InH	R/WS	Fault inhibit Factory setting: 0  Inhibiting faults may damage the drive beyond repair. This would invalidate the guarantee. 0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6 Fault monitoring is active when the input is at state 0. It is inactive when the input is at state 1. All active faults are reset on a rising edge (from 0 to 1) of the input.
3120	2001 / 15	rPr	R/WS	Operating time reset to zero Factory setting: 0 0 = "nO": No 2 = "rtH": Operating time reset to zero The rPr parameter automatically falls back to nO as soon as the reset to zero is performed.

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
6001	201E / 2	Add	R/WS	Modbus: Drive address Unit: 1 Factory setting: 1 Adjustment range: 1 to 247
6001	201E / 2	Add	R/WS	Modbus: Drive address Unit: 1 Factory setting: 1 Adjustment range: 1 to 247
6003	201E / 4	tbr	R/WS	Modbus: Transmission speed Factory setting: 32 24 = "4.8" : 4800 bps 28 = "9.6" : 9600 bps 32 = "19.2": 19200 bps (Caution: The remote display terminal can only be used with this value.)
6004	201E / 5	tFO	R/WS	Modbus: communication format Factory setting: 3 2 = "8O1": 8 data bits, odd parity, 1 stop bit 3 = "8E1": 8 data bits, even parity, 1 stop bit (Caution: The remote display terminal can only be used with this value.) 4 = "8n1": 8 data bits, no parity, 1 stop bit 5 = "8n2": 8 data bits, no parity, 2 stop bits
6005	201E / 6	ttO	R/WS	Modbus: Time-out Unit: 0.1 s Factory setting: 100 Adjustment range: 1 to 100
6051	201E / 34	AdCO	R/WS	CANopen: Drive address Unit: 1 Factory setting: 0 Adjustment range: 0 to 127
6053	201E / 36	bdCO	R/WS	CANopen: Transmission speed Factory setting: 52 30 = "10.0": 10 kbps 34 = "20.0": 20 kbps 38 = "50.0": 50 kbps 52 = "125.0": 125 kbps 60 = "250.0": 250 kbps 68 = "500.0": 500 kbps 76 = "1000": 1000 kbps
8431	2036 / 20	FLO	R/WS	Forced local mode Factory setting: 0 0 = "nO": Not assigned 129 = "LI1": Logic input LI1 130 = "LI2": Logic input LI2 131 = "LI3": Logic input LI3 132 = "LI4": Logic input LI4 133 = "LI5": Logic input LI5 134 = "LI6": Logic input LI6 In forced local mode, the terminal block or display terminal regains control of the drive.
8432	2036 / 21	FLOC	R/WS	Selection of the reference and control channel in forced local mode Active only if LAC = 3 Factory setting: 1 except for ATV31●●●A: 16 In forced local mode, only the speed reference is taken into account. PI functions, summing inputs, etc. are not active. 1 = "AI1": Analog input AI1, logic inputs LI 2 = "AI2": Analog input AI2, logic inputs LI 3 = "AI3": Analog input AI3, logic inputs LI 16 = "AIP": Potentiometer (type A drives only), RUN, STOP buttons 163 = "LCC": Remote display terminal: LFr reference page 14, RUN, STOP, FWD/REV buttons.

Configuration and adjustment variables

Modbus address	CANopen address	Code	Read/Write	Name/Description/Possible values
3003	2000 / 4	COd	R/W	<p>Display terminal locking code Enables the drive configuration to be protected using an access code.</p> <p> Caution: Before entering a code, do not forget to make a careful note of it.</p> <p>0 = OFF: No access locking codes</p> <ul style="list-style-type: none"> - To lock access, enter a code (2 to 9999). "On" appears on the screen to indicate that the parameters have been locked. <p>1 = On: A code is locking access (2 to 9999)</p> <ul style="list-style-type: none"> - To unlock access, enter the code. The code remains on the display and access is unlocked until the next power down. Parameter access will be locked again on the next power-up. - If an incorrect code is entered, COd changes to "On" and the parameters remain locked. <p>2 to 9999: Parameter access is unlocked (the code remains on the screen).</p> <ul style="list-style-type: none"> - To reactivate locking with the same code when the parameters have been unlocked, return to "On". - To lock access with a new code when the parameters have been unlocked, enter the new code. - To disable locking when the parameters have been unlocked, return to "OFF". <p>When access is locked using a code, only the monitoring parameters can be accessed, with only a temporary choice of parameter displayed.</p>

Replacing an ATV28 with an ATV31

If necessary, it is easy to replace an ATV28 with a ATV31 in an installation communicating via Modbus. In fact, most of the variables used in the ATV28 are found in the ATV31 with the same addresses (double addressing).

- To replace an ATV28, the ATV28 addresses in this table can be used, but **only these. All the other ATV28 addresses must be replaced** with those for the ATV31.
- For any new installation, we recommend using the new addresses, as this enables the number of Modbus requests to be reduced.

ATV 28 address	New address	Code	ATV 28 address	New address	Code	ATV 28 address	New address	Code
2	3003	COd	266	11412	SP4	462	7201	DP1
4	4434	CrL3	267	11413	SP5	464	7202	DP2
5	4444	CrH3	268	11414	SP6	466	7203	DP3
6	11101	tCC	269	11415	SP7	468	7204	DP4
10	6001	Add	270	11210	ldC	478	5240	IOLR
40	3015	bFr	272	11701	tLS	482	5261	AO1R
51	3102	SFr	279	11941	rPG	487	3208	Otr
52	3103	tFr	280	11942	rIG	491	3211	OPr
53	9602	FrS	281	11903	FbS	530	3231	rtH
55	9601	UnS	282	11001	Ctd	555	3017	INV
60	3107	nrd	283	11002	ttd	600	8606	ERRD
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(1) See the ATV28 communication variables manual.

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